





# An Improved Zero-Switching-Loss Inverter With Low Conduction Loss

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**Abstract**—Zero-switching-loss (ZSL) transformerless inverter (TLI) is beneficial for increasing switching frequency for distributed photovoltaic generation systems. However, the existing ZSL-TLIs bear high conduction loss because of the coupling between the resonance tanks and the main power loops. In order to solve this problem, an improved zero-switching-loss H6 inverter (IZSL-H6) with low conduction loss composed of novel resonance tanks and an H6 inverter has been proposed in this article. The resonance tanks provide zero-current switching (ZCS) for H6 inverter switches, and the auxiliary devices of the resonance tanks are also turned ON and OFF with ZCS. Compared with the existing ZSL-H6, IZSL-H6 reduces conduction loss by avoiding resonant current flow through the main switches during resonant capacitor charging mode and reducing the number of power devices in the main power loops during the freewheeling mode. Resonant parameters design, soft-switching criteria, and common-mode voltage characteristics are discussed. Finally, a 1000-W prototype has been developed to verify the theoretical analysis of the proposed IZSL-H6.

**Index Terms**—Conduction loss, resonance tank, transformerless inverter (TLI), zero-switching-loss (ZSL).

## I. INTRODUCTION

IN RECENT years, with the increasing demand for energy and growing environmental awareness, solar energy, as a renewable clean energy, has received widespread attention and application [1], [2], [3]. The decentralized layout of distributed photovoltaic (PV) power generation systems has the advantages of strong adaptability, flexible installation, and high reliability, which has contributed to increase the share of PV power generation applications [4], [5].

A transformerless inverter (TLI) with low cost, high efficiency, and compact size is suitable for distributed PV power generation systems [6]. The full-bridge inverter is a TLI, with

the advantages of higher input voltage utilization, higher conversion efficiency, and smaller output current under unipolar sinusoidal pulsewidth modulation (SPWM) [7], [8]. However, serious safety issues arise due to the common-mode (CM) leakage current (LC) generated by parasitic capacitors between PV panels and the ground so that this kind of inverter cannot be directly equipped in PV power generation systems [9], [10]. In order to improve the LC suppression capability of unipolar SPWM full-bridge TLI, extensive research was carried out in [11], [12], [13], and [14], categorizing into dc bypass and ac bypass. For example, H6 inverter is obtained by connecting a switch in series at the positive and negative points of the dc link in a full-bridge inverter [11]. In addition, a pair of reverse series switches is added at the midpoint of the bridge leg in the full-bridge inverter to obtain the HERIC inverter [13]. This type of bypass inverter effectively reduces LC by interrupting the electrical connection between dc link and ac side and cutting off the CM loop in the freewheeling mode. However, the bypass-type inverter is unable to completely eliminate high-frequency LC due to fluctuations in CM voltage.

Based on the CM analytical model at switching frequency in [15], maintaining a constant CM voltage is an effective method to eliminate LC in full-bridge inverter with unipolar SPWM. The existing TLI with the clamp structure has shown good performance in suppressing LC under unipolar output conditions due to maintaining a constant CM voltage value in freewheeling mode [16], [17], [18], [19], [20], [21]. However, bypass-type inverters and clamp-type inverters typically employ hard-switching (HS), and the switching frequency is limited considering switching loss, resulting in an increase in filter size and cost, and a corresponding decrease in system power density.

Soft-switching technology can reduce or even eliminate switching loss, which is an important approach to improve efficiency and promote high-frequency operation [22], [23]. Resonant dc-link inverter (RDCLI) and resonant pole inverter proposed by Divan and Skibinski [24], [25] have pioneered the application of soft-switching technology in dc–ac inverters, and thus expanded a series of soft-switching inverters [26], [27], [28], [29], [30], [31], [32]. The active clamp RDCLI in [29] and [30] provides zero-voltage switching (ZVS) of the switches through an auxiliary circuit connected in series on the dc link, which reduces drain–source voltage to zero before turning ON the switches. Adding the auxiliary circuit on ac side is also a means to achieve ZVS. The soft-switching inverters proposed in [31] and [32] use the filtering inductor as the magnetic inductor

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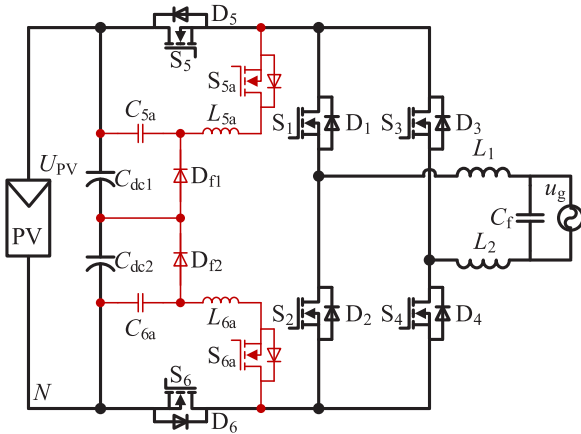


Fig. 1. ZSL-H6 inverter in [35].

and the leakage inductor as the resonant inductor, which can achieve ZVS of the main switches and zero-current switching (ZCS) of the auxiliary switches. However, the above inverters are not directly applicable to transformerless PV power generation systems, as the focus is on the implementation of soft switching and the CM voltage has not been considered. A series of novel freewheeling resonance tank inverters for TLI has been proposed by Xiao et al. [33], [34], [35]. The zero-voltage-transition (ZVT) inverter proposed in [33] achieves ZVT of the high-frequency main switches and zero-current turn-ON of the added auxiliary switches, and obtains a constant CM voltage under unipolar SPWM through the freewheeling resonance tanks. However, the auxiliary switches were hard turn-OFF. In addition, the zero-current-transition inverter proposed in [34] achieved zero-current turn-OFF of the main switches and zero-voltage turn-ON for the auxiliary switches. Addressing the issues of hard turn-OFF for the main switches and reverse recovery of diodes in [34], novel resonance tanks were proposed in [35]. Zero switching loss (ZSL) of the high-frequency power devices in clamp-type hard-switching H6 (HS-H6) proposed in [17] and other full-bridge inverters can be achieved due to the application of these resonance tanks, ZSL-H6 is shown in Fig. 1. However, due to the coupling between the resonant tanks and the main power loops, the number of power devices in [35] flowing through by the resonant current is relatively large. It leads to more conduction loss and a doubling of the current amplitude of the main switches.

This article focuses on reducing the conduction loss of existing ZSL inverters by introducing a novel resonant tank in H6 to achieve ZSL. The proposed improved zero-switching-loss H6 inverter (IZSL-H6) has excellent performance in LC suppression due to the CM voltage being clamped at a constant value. Compared with ZSL-H6 in [35], IZSL-H6 effectively separates the resonance tanks and the main power loops at all stages except for the soft-switching stages. Specifically, during resonant capacitor charging mode, the resonant currents in IZSL-H6 bypass the main switches, avoiding the doubling of current amplitude and, consequently, reducing conduction loss; during the freewheeling mode, reducing the number of power devices through which the output current flows can further decrease conduction loss.

The rest of this article is organized as follows. Section II introduces the structure and operation principle of the proposed IZSL-H6. The state-plane trajectory, voltage and current stresses, and conduction loss of power devices of ZSL-H6 and IZSL-H6 are compared in Section III. Section IV analyzes the soft-switching criteria and CM characteristics. The experimental results of a 1000-W prototype are provided in Section V. Finally, Section VI concludes this article.

## II. CIRCUIT STRUCTURE AND OPERATION PRINCIPLE

The IZSL-H6 inverter is shown in Fig. 2(a). The main circuit consists of dc-link capacitors  $C_{dc1}$  and  $C_{dc2}$ , main switches  $S_1$ – $S_6$ , and output filter inductors  $L_1$  and  $L_2$ , where  $L_1 = L_2$ , and a filter capacitor  $C_f$ . The resonance tanks are composed of resonant inductors  $L_{5a}$  and  $L_{6a}$ , resonant capacitors  $C_{5a}$  and  $C_{6a}$ , auxiliary switches  $S_{5a}$  and  $S_{6a}$ , freewheeling diodes  $D_{f1}$  and  $D_{f2}$ , and auxiliary diodes  $D_{a1}$  and  $D_{a2}$ , where  $L_{5a} = L_{6a} = L_r$  and  $C_{5a} = C_{6a} = C_r$ . The modulation strategy employed by IZSL-H6 is illustrated in Fig. 2(b), where the main switches  $S_1$  and  $S_4$  turn ON during the positive half-cycle of the grid frequency, while the main switches  $S_2$  and  $S_3$  turn ON during the negative half-cycle of the grid frequency, and both the main switches  $S_5$  and  $S_6$  and auxiliary switches  $S_{5a}$  and  $S_{6a}$  operate at high frequency throughout the entire grid-frequency cycle. Fig. 2(c) shows the key waveforms at the switching-frequency scale. Within a complete switching cycle of the main switches  $S_5$  and  $S_6$ , there are eight operational stages, as illustrated in Fig. 3, which depict the equivalent circuit for each stage and highlight the key features.

*Stage 1* [ $t_0, t_1$ ]: Before  $t_0$ , IZSL-H6 operates in the freewheeling mode, and the resonant current is equal to the output current, flowing through  $L_{5a}$ ,  $L_{6a}$ ,  $D_{f1}$ , and  $D_{f2}$ . The resonant voltages  $u_{C_{5a}}$  and  $u_{C_{6a}}$  across  $C_{5a}$  and  $C_{6a}$  are both zero. Refer to Fig. 3(a), at  $t_0$ ,  $S_5$  and  $S_6$  are turned ON, and the resonant currents  $i_{L_{5a}}$  and  $i_{L_{6a}}$  through  $L_{5a}$  and  $L_{6a}$  decrease linearly with a constant slope. The slope is determined by the input voltage  $U_{PV}$  and the resonant inductance  $L_r$ . Simultaneously, the currents  $i_{S_5}$  and  $i_{S_6}$  through  $S_5$  and  $S_6$  increase at the same slope, achieving ZCS turn-ON for  $S_5$  and  $S_6$ . At this stage

$$i_{L_{5a}, L_{6a}}(t) = i_{D_{f1}, D_{f2}}(t) = I_L - \frac{U_{PV}}{2L_r}(t - t_0) \quad (1)$$

$$i_{S_5, S_6}(t) = \frac{U_{PV}}{2L_r}(t - t_0). \quad (2)$$

*Stage 2* [ $t_1, t_2$ ]: Refer to Fig. 3(b), at  $t_1$ , the currents  $i_{S_5}$  and  $i_{S_6}$  rise to the amplitude  $I_L$  of the output current, while the currents  $i_{D_{f1}}$  and  $i_{D_{f2}}$  through  $D_{f1}$  and  $D_{f2}$  decrease to zero. Therefore,  $D_{f1}$  and  $D_{f2}$  achieve ZCS turn-OFF, effectively eliminating the reverse recovery issue. Subsequently, the inverter enters the conventional energy transfer mode. At this stage

$$i_{S_5, S_6}(t) = I_L. \quad (3)$$

*Stage 3* [ $t_2, t_3$ ]: Refer to Fig. 3(c), at  $t_2$ , the resonance tanks are activated due to  $S_{5a}$  and  $S_{6a}$  turning ON. The voltages  $u_{C_{5a}}$  and  $u_{C_{6a}}$ , as well as the currents  $i_{L_{5a}}$  and  $i_{L_{6a}}$ , begin to increase from zero under the action of  $U_{PV}$ . The currents  $i_{S_{5a}}$  and  $i_{S_{6a}}$

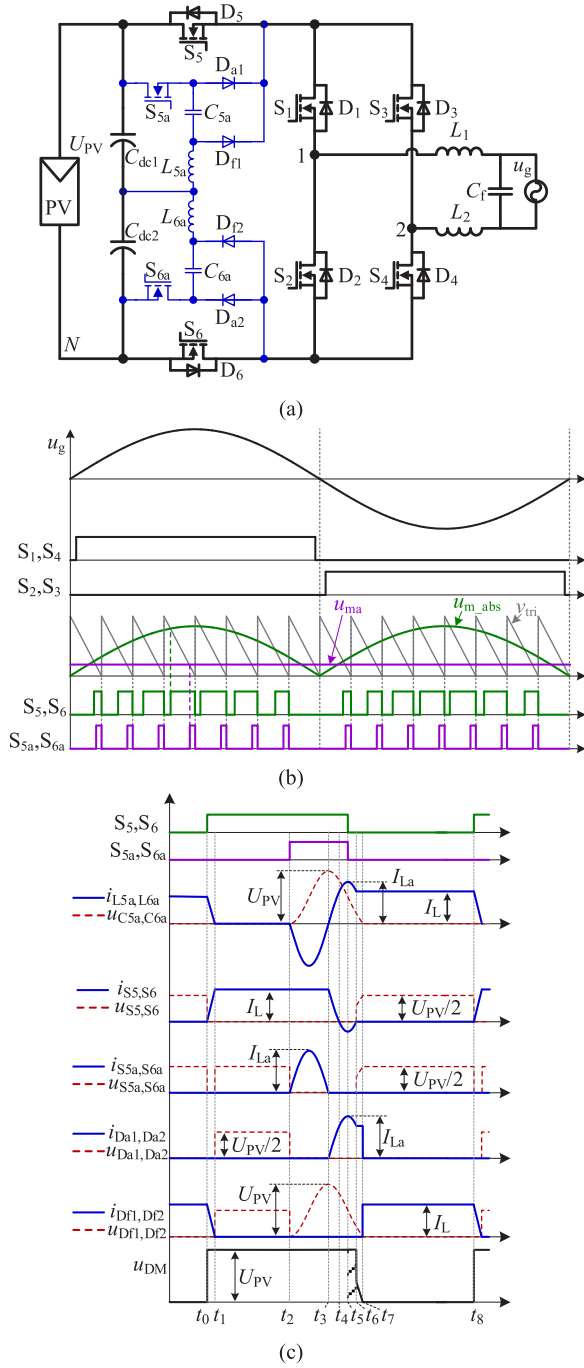


Fig. 2. Proposed IZSL-H6 inverter. (a) IZSL-H6. (b) Driving logic at the grid-frequency scale. (c) Key waveforms at the switching-frequency scale.

of  $S_{5a}$  and  $S_{6a}$  are equal to  $i_{L5a}$  and  $i_{L6a}$ , resulting in the ZCS turn-ON of  $S_{5a}$  and  $S_{6a}$ . Once  $i_{L5a}$  and  $i_{L6a}$  reach the amplitude  $I_{La}$  of the resonant current, they start to decrease. By  $t_3$ , the resonance tanks have completed half of a cycle. The voltages  $u_{C5a}$  and  $u_{C6a}$  have reached the amplitude  $U_{PV}$  of the resonant voltage, and the currents  $i_{L5a}$  and  $i_{L6a}$  have decreased to zero.  $S_{5a}$  and  $S_{6a}$  achieve ZCS turn-OFF. At this stage

$$i_{L5a, L6a}(t) = -I_{La} \sin \omega_r(t - t_2) \quad (4)$$

$$u_{C5a, C6a} = \frac{U_{PV}}{2} [1 - \cos \omega_r(t - t_2)] \quad (5)$$

where  $\omega_r = 1/\sqrt{L_r C_r}$  and  $I_{La} = U_{PV}/2/Z_r = U_{PV}/(2\sqrt{L_r/C_r})$ .

*Stage 4* [ $t_3, t_4$ ]: Refer to Fig. 3(d), at  $t_3$ , the resonance tanks enter the three-quarter cycle. The voltages  $u_{C5a}$  and  $u_{C6a}$  start decreasing from  $U_{PV}$ , while the currents  $i_{L5a}$  and  $i_{L6a}$  increase from zero. The currents of  $D_{a1}$  and  $D_{a2}$  are equal to  $i_{L5a}$  and  $i_{L6a}$ . Simultaneously, the currents  $i_{S5}$  and  $i_{S6}$  decrease from  $I_L$  due to the influence of  $i_{L5a}$  and  $i_{L6a}$

$$i_{S5, S6}(t) = I_L - i_{L5a, L6a}(t). \quad (6)$$

*Stage 5* [ $t_4, t_5$ ]: Refer to Fig. 3(e), at  $t_4$ , the currents  $i_{L5a}$  and  $i_{L6a}$  increase to  $I_L$  and continue to rise. Once the currents  $i_{S5}$  and  $i_{S6}$  decrease to zero, the antiparallel diodes  $D_5$  and  $D_6$  of  $S_5$  and  $S_6$  begin to conduct, causing the currents  $i_{S5}$  and  $i_{S6}$  to increase from zero to the opposite direction. Meanwhile, the voltages  $u_{C5a}$  and  $u_{C6a}$  continue to decrease. By  $t_5$ , the currents  $i_{L5a}$  and  $i_{L6a}$  have reached the amplitude  $I_{La}$ . After  $t_4$ ,  $S_5$  and  $S_6$  meet the conditions for ZCS turn-OFF.

*Stage 6* [ $t_5, t_6$ ]: Refer to Fig. 3(f), at  $t_5$ , the currents  $i_{S5}$  and  $i_{S6}$  decrease to  $I_L - I_{La}$  and then begin to increase until they reach zero at  $t_6$ . Simultaneously, the currents  $i_{L5a}$  and  $i_{L6a}$  gradually decrease from  $I_{La}$  to  $I_L$ , and the voltages  $u_{C5a}$  and  $u_{C6a}$  continue to decrease.

*Stage 7* [ $t_6, t_7$ ]: Refer to Fig. 3(g), at  $t_6$ ,  $S_5$  and  $S_6$  are completely turned OFF. The currents  $i_{L5a}$  and  $i_{L6a}$  become equal to  $I_L$ , and the resonant capacitors  $C_{5a}$  and  $C_{6a}$  discharge through  $D_{a1}$  and  $D_{a2}$  with a discharge current of  $I_L$ . At this stage

$$i_{L5a, L6a}(t) = I_L \quad (7)$$

$$u_{C5a, C6a}(t) = \frac{U_{PV}}{2} \left[ 1 - \cos \left( \arcsin \left( -\frac{I_L}{I_{La}} \right) \right) \right] - \frac{I_L}{C_r} (t - t_6). \quad (8)$$

*Stage 8* [ $t_7, t_8$ ]: Refer to Fig. 3(h), at  $t_7$ , the discharge of  $C_{5a}$  and  $C_{6a}$  is completed, and  $u_{C5a}$  and  $u_{C6a}$  drop to zero.  $D_{a1}$  and  $D_{a2}$  achieve ZCS turn-OFF.  $D_{f1}$  and  $D_{f2}$  enable ZCS turn-ON, providing a continuous path for the resonant current  $I_{La}$ , as well as the inverter enters the conventional freewheeling mode. Starting from  $t_8$ , a new switching cycle begins and the above operation described is repeated.

### III. COMPARISON OF ZSL-H6 AND IZSL-H6

#### A. Comparison of State-Plane Trajectory

Taking the upper resonant tank as an example, the modes of ZSL-H6 and IZSL-H6 can be summarized, as shown in Table I. It is important to note that the order of modes in the table does not necessarily correspond to the sequence of circuit operations. From Table I, the common feature between ZSL-H6 and IZSL-H6 is achieving ZCS turn-ON and turn-OFF for the main switch  $S_5$  by transferring the output current  $i_L$  between the resonant tank and the main power loop. Combining the state-plane trajectory in Fig. 4 and Table I, analyze in detail the performance improvements of IZSL-H6 compared with ZSL-H6.

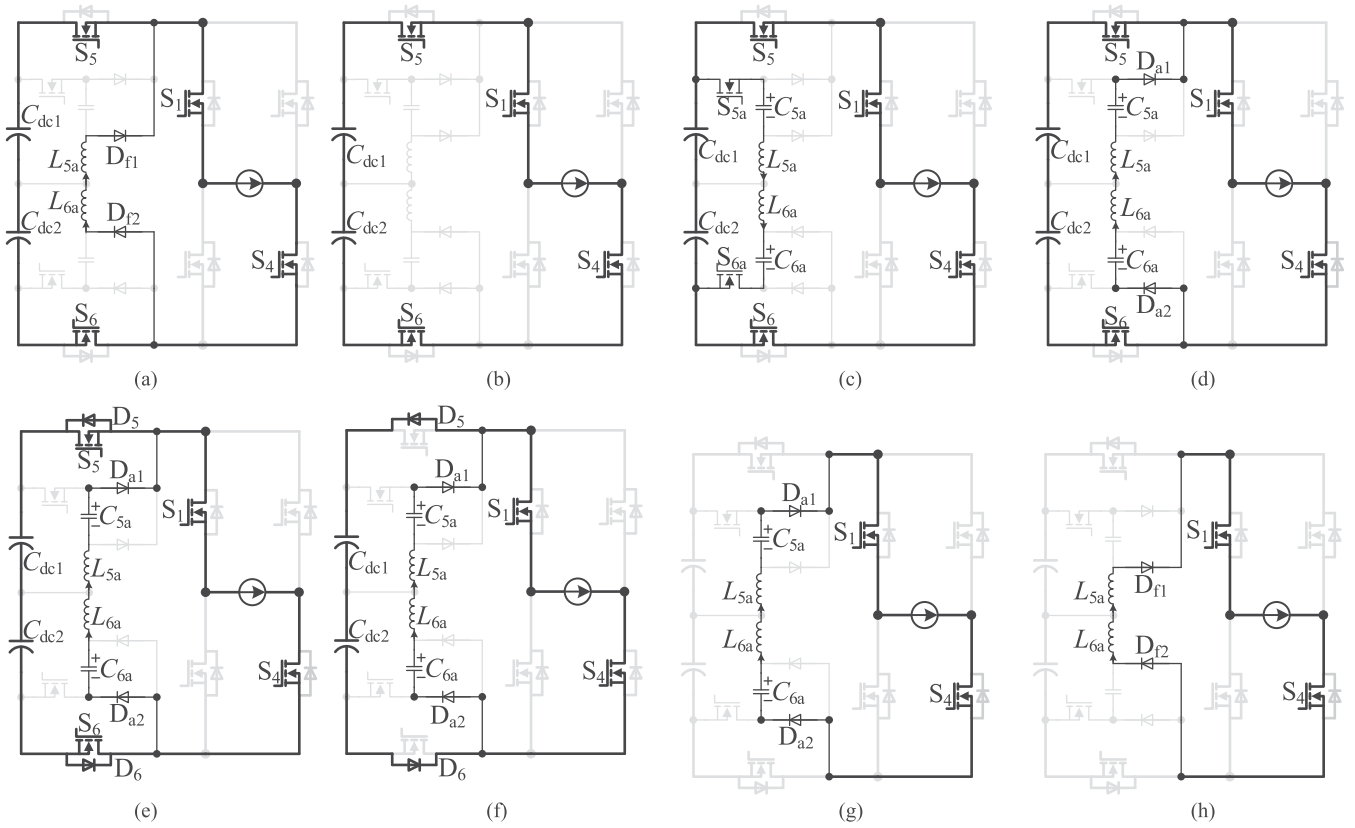


Fig. 3. Equivalent circuits in a positive half cycle. (a) Stage 1 [ $t_0, t_1$ ]. (b) Stage 2 [ $t_1, t_2$ ]. (c) Stage 3 [ $t_2, t_3$ ]. (d) Stage 4 [ $t_3, t_4$ ]. (e) Stage 5 [ $t_4, t_5$ ]. (f) Stage 6 [ $t_5, t_6$ ]. (g) Stage 7 [ $t_6, t_7$ ]. (h) Stage 8 [ $t_7, t_8$ ].

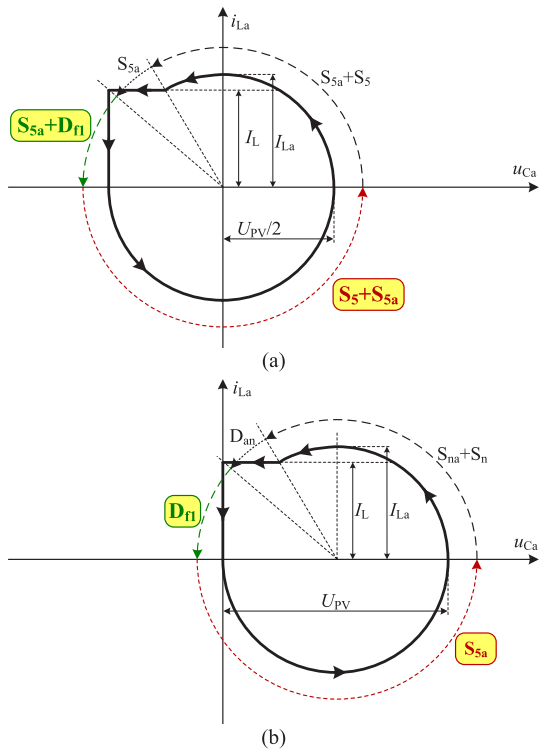


Fig. 4. State-plane trajectory. (a) State-plane trajectory of ZSL-H6 in [35]. (b) State-plane trajectory of the proposed IZSL-H6.

TABLE I  
SUMMARY OF OPERATING MODES OF ZSL-H6 AND IZSL-H6

	ZSL-H6	IZSL-H6
Energy transfer mode	$i_L$ flows through $S_5$ . Resonance tank does not operate.	
Soft-switching mode	$i_L$ is transferred from resonance tank to main power loop. $S_5$ achieves ZCS turn-on.	
Soft-switching mode	$i_L$ is transferred from the main power loop to resonance tank.	
Resonant capacitor charging mode	$i_{Lr}$ flows through $S_{5a}$ and $S_5$ . $S_{5a}$ ZCS turn-on.	$i_{Lr}$ flows through $S_{5a}$ . $S_{5a}$ ZCS turn-on and turn-off.
Freewheeling mode	$i_L$ flowing through $D_{f1}$ and $S_{5a}$ .	$i_L$ flowing through $D_{f1}$ .

1) In the resonant capacitor charging mode (the red dashed arc), the resonant current  $i_{Lr}$  flows through the auxiliary switch  $S_{5a}$  and the main switch  $S_5$  of ZSL-H6. As a result, the current of the main switch  $S_5$  is the sum of the output current and the resonant current. It increases the current amplitude on  $S_5$  by at least twice the output current amplitude, thereby increasing the conduction loss. In contrast, the state-plane trajectory of IZSL-H6 demonstrates

TABLE II  
COMPONENT QUANTITY AND VOLTAGE RATE

	Voltage Rating	HS-H6	ZSL-H6	IZSL-H6
Main switch	$U_{PV}$	4	4	4
Auxiliary switch	$U_{PV}/2$	2	2	2
Diode	$U_{PV}$	0	2	2
	$U_{PV}/2$	0	2	2

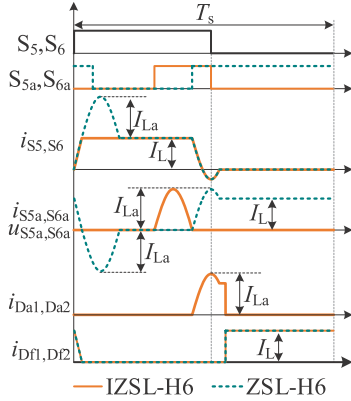


Fig. 5. Current waveforms of high-frequency semiconductor power devices of ZSL-H6 in [35] and IZSL-H6 during a switching cycle.

that the resonant current only flows through the auxiliary switch  $S_{5a}$ . The current amplitude and conduction loss of the main switch  $S_5$  can be effectively reduced due to the approach.

- In the freewheeling mode (the green dashed arc), the resonant current is equal to the output current, flowing through the freewheeling diode  $D_{f1}$  and the auxiliary switch  $S_{5a}$  of ZSL-H6. In contrast, the proposed state-plane trajectory indicates that the output current solely flows through the freewheeling diode  $D_{f1}$ , which can further reduce conduction loss.

### B. Comparison of Voltage and Current Stresses

The comparison of power device count and voltage stress in HS-H6, ZSL-H6, and IZSL-H6 is presented in Table II. Compared with HS-H6, ZSL-H6 includes two additional switches with a voltage stress of  $U_{PV}/2$  while maintaining the same number of diodes but raising the voltage stress from  $U_{PV}/2$  to  $U_{PV}$ . IZSL-H6 introduces two diodes with a voltage stress of  $U_{PV}/2$  compared with ZSL-H6, while the number of other devices and their respective voltage stresses have not changed.

The current waveforms of the power devices within one switching cycle in ZSL-H6 and IZSL-H6 are shown in Fig. 5. It can be observed that the current amplitude of high-frequency main switches  $S_5$  and  $S_6$  in ZSL-H6 is  $I_{La} + I_L > 2I_L$ , which increases the conduction loss. In contrast, the current amplitudes of the main switches  $S_5$  and  $S_6$  in IZSL-H6 are equal to the output current amplitude  $I_L$ , and the maximum current of all power devices does not exceed the amplitude  $I_{La}$  of the resonant current. During the turn-OFF phase of the main switches  $S_5$  and

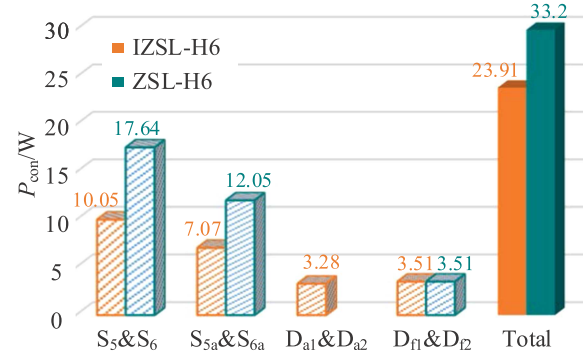


Fig. 6. Conduction loss of high-frequency semiconductor power devices of ZSL-H6 and proposed IZSL-H6.

$S_6$ , the output current flows through the freewheeling diodes  $D_{f1}$  and  $D_{f2}$  in IZSL-H6. However, in ZSL-H6, the output current not only flows through  $D_{f1}$  and  $D_{f2}$  but also through the auxiliary switches  $S_{5a}$  and  $S_{6a}$ , resulting in an inevitable increase in conduction loss. A quantitative comparison of the conduction loss will be presented in subsequent research analyses.

### C. Conduction Loss of High-Frequency Power Devices

To quantitatively compare the conduction loss between ZSL-H6 and IZSL-H6, the conduction loss of the high-frequency power devices was calculated while disregarding the low-frequency switches  $S_1$ – $S_4$  operating in the same mode. Based on the current waveform, as shown in Fig. 2(c), calculate the results according to (9), as shown in Fig. 6. The results clearly demonstrate that IZSL-H6 exhibits lower overall conduction loss compared with ZSL-H6

$$P_{\text{con}, S_5} = I_{S_5, \text{rms}}^2 R_{\text{on}} = \frac{1}{\pi} \int_0^\pi \left[ \frac{1}{T_s} \int_{t_0}^{t_s} i_{S_5}(t) dt \right] dt R_{\text{on}}. \quad (9)$$

## IV. PERFORMANCE ANALYSIS

### A. Parameters Design of Resonance Tank and Soft-Switching Criteria

Based on the analysis of operation principles in Section II, the following are detailed design guidelines for the parameters design of the resonance tank.

1) *Value range of  $L_r$  and  $C_r$* : Under the constraint of resonant current, once the main switches  $S_5$  and  $S_6$  are turned ON, their current rises with a constant slope to achieve ZCS turn-ON. Before turning OFF  $S_5$  and  $S_6$ , it is necessary to turn ON the auxiliary switches  $S_{5a}$  and  $S_{6a}$  to activate the resonance tanks. It facilitates the transfer of the current flowing through  $S_5$  and  $S_6$  to the resonance tanks, ultimately enabling the ZCS turn-OFF of  $S_5$  and  $S_6$ . Therefore, it is a requirement that the amplitude  $I_{La}$  of the resonant current should be greater than the amplitude  $I_L$  of the output current

$$I_{La} = \frac{U_{PV}}{2Z_r} = \frac{U_{PV}}{2\sqrt{L_r/C_r}} > I_L. \quad (10)$$

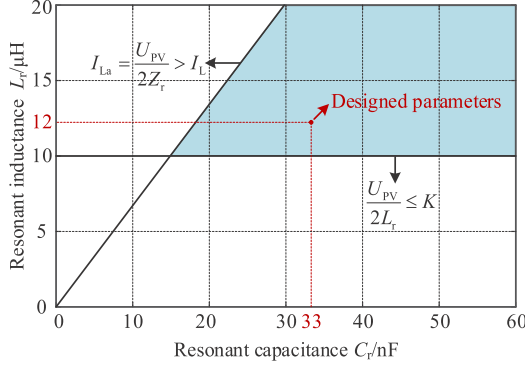


Fig. 7. Design of resonant parameters in IZSL-H6.

According to (2), the current of the main switches is constrained by the resonant inductance  $L_r$ . The rate of current rise  $K$  is associated with the rated power of the power device. Typically,  $K$  is less than  $40 \text{ A}/\mu\text{s}$ , and with a 100% margin considered,  $K$  is set to  $20 \text{ A}/\mu\text{s}$

$$\frac{U_{PV}}{2L_r} \leq K. \quad (11)$$

Under the constraints of (10) and (11), suitable resonant parameters for IZSL-H6 can be chosen within the shaded region in Fig. 7.

2) *Design consideration of  $L_r$* : The resonant inductance  $L_r$  determines the rate of current rise. A larger  $L_r$  will increase the length of the interval  $[t_0, t_1]$ , thereby raising the losses in the resonant tank. Therefore, based on the range of resonant parameters obtained in Step 1, choose a smaller inductance, preferably  $10 \mu\text{H}$ . Considering inevitable errors in inductor winding, with a margin of 20%,  $L_r$  is selected as  $12 \mu\text{H}$ .

3) *Design consideration of  $C_r$* : After determining  $L_r$  in Step 2, it can be inferred that considering a margin for  $L_r$  will reduce the resonant current amplitude according to (10). Due to the inevitable parasitic parameters in the circuit, the actual resonant current amplitude is smaller than the theoretical value. To ensure that the resonant current amplitude is greater than the output current, it is necessary to provide an additional margin for  $C_r$ . Therefore, a resonant capacitor of  $33 \text{ nF}$  is selected.

Referring to Fig. 2(c), it can be seen that the auxiliary switches flow current within the interval  $[t_2, t_3]$ , covering half of the resonance period  $T_r$ . Therefore, the conduction time  $d_a T_s$  of the auxiliary switches must exceed  $0.5T_r$  to ensure a ZCS turn-OFF. In the normal operation of IZSL-H6, the turn-OFF of the auxiliary switches should not occur after the turn-OFF of the main switches. The turn-OFF of the main switches within the interval  $[t_4, t_6]$  is a prerequisite for achieving ZCS turn-OFF. To simplify control, the main switches and auxiliary switches can use the same sawtooth wave to generate a driving signal, and both can be turned OFF simultaneously, as depicted in Fig. 2(c). Therefore, the turn-OFF time of the auxiliary switches also falls within the interval  $[t_4, t_6]$ . In summary, the range of conduction time  $d_a T_s$  can be expressed as follows:

$$\frac{1}{2}T_r < d_a T_s < \frac{3}{4}T_r + \frac{1}{\omega_r} \arcsin\left(\frac{I_L}{I_{La}}\right) \quad (12)$$

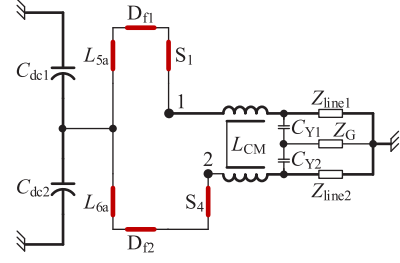


Fig. 8. CM equivalent circuit in the freewheeling-clamping mode.

TABLE III  
SWITCHING STAGES, DM VOLTAGES, AND CM VOLTAGES

Switch Stage	$u_{1N}$	$u_{2N}$	$u_{DM}$	$u_{CM}$
$[t_0, t_6]$	$U_{PV}$	0	$U_{PV}$	$U_{PV}/2$
$[t_6, t_7]$	$U_{PV}/2 + u_{C5a}$	$U_{PV}/2 - u_{C6a}$	$2u_{C5a}$	$U_{PV}/2$
$[t_7, t_8]$	$U_{PV}/2$	$U_{PV}/2$	0	$U_{PV}/2$

where the resonant period  $T_r = 2\pi\sqrt{L_r C_r}$ .

The main switches and auxiliary switches can be turned OFF in the middle of the interval  $[t_4, t_6]$  so that the conduction time of the auxiliary switches  $S_{5a}$  and  $S_{6a}$  can be fixed at  $3T_r/4$ .

### B. CM Characteristic and Differential-Mode (DM) Compensation

The CM equivalent circuit in the freewheeling-clamping mode is introduced in Section II, as shown in Fig. 8. In this mode, the clamping branch is responsible for clamping the midpoints 1 and 2 of the bridge arms at a constant voltage, which can achieve a constant CM voltage and suppressing LC. Ignoring the current ripple in the output filter inductor at the switching frequency, the DM voltage  $u_{DM}$  and CM voltage  $u_{CM}$  of IZSL-H6 within one switching cycle can be represented in Table III, where  $u_{DM} = u_{1N} - u_{2N}$ ,  $u_{CM} = (u_{1N} + u_{2N})/2$ . An important observation is that  $u_{CM}$  remains constant and  $u_{DM}$  is unipolar output.

As shown in Fig. 2(c), the operation of the resonant tank affects the DM voltage  $u_{DM}$  of IZSL-H6, causing the equivalent duty cycle of  $u_{DM}$  to deviate from sine. To eliminate this effect, compensation for the duty cycle of the main switches  $S_5$  and  $S_6$  is employed. Therefore, the equivalent area of the shaded part can be subtracted from the modulated wave. The calculated compensation amount can be expressed as follows:

$$\Delta d(t) = \frac{\cos^{-1}\left(\frac{i_{ref}(t)}{I_{La}}\right) \sqrt{L_r C_r} + \frac{C_r U_{PV}}{4i_{ref}(t)} \left[1 - \sqrt{1 - \left(\frac{i_{ref}(t)}{I_{La}}\right)^2}\right]^2}{T_s}. \quad (13)$$

## V. EXPERIMENTAL RESULTS AND DISCUSSIONS

To verify the operation principle and effectiveness of the proposed IZSL-H6, a 1000-W experimental prototype was constructed in the laboratory. The prototype parameters are presented in Table IV, and the experimental setup is shown in Fig. 9.

TABLE IV  
PARAMETERS OF 1000-W PROTOTYPE

Parameter	Value		
	HS-H6	ZSL-H6	IZSL-H6
Input voltage $U_{PV}$		400 V	
Grid voltage $u_g$		220 V	
Grid frequency		50 Hz	
Rated power $P$		1000 W	
Switching frequency $f_s$		50 kHz	
Power devices $S_1$ – $S_6$		G3R350MT12D	
Diode $D_{f1}$ , $D_{f2}$		MUR3060PT	
Filter inductance $L_1$ , $L_2$		0.5 mH	
Filter capacitance $C_f$		2 $\mu$ F	
Power devices $S_{5a}$ , $S_{6a}$	/	G3R350MT12D	G3R350MT12D
Diode $D_{a1}$ , $D_{a2}$	/	/	MUR3060PT
Resonant inductance $L_r$	/	12 $\mu$ H	12 $\mu$ H
Resonant capacitance $C_r$	/	33 nF	33 nF

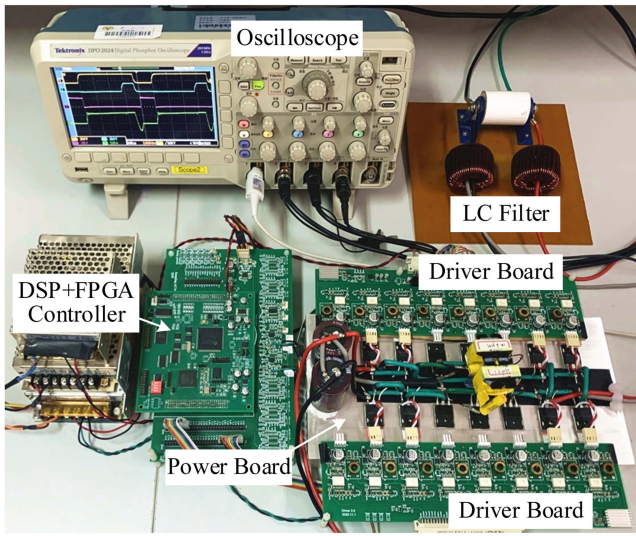


Fig. 9. Experimental setup of the IZSL-H6 inverter.

### A. Verification of the DM Performance

The DM characteristics of IZSL-H6 under rated power are shown in Fig. 10. In Fig. 10(a), the experimental waveforms of grid voltage  $u_g$ , output current  $i_L$ , and DM voltage  $u_{DM}$  are shown on the grid-frequency scale. It can be observed that the DM voltage exhibits unipolar output characteristics. Fig. 10(b) and (c) represents the experimental waveforms of  $i_L$  and  $u_{DM}$  at the switching-frequency scale in the positive and negative half-cycles of the grid, respectively.

### B. Verification of the CM Performance

Fig. 11 illustrates the experimental waveforms of CM characteristics of IZSL-H6 under rated power. Fig. 11(a) shows the experimental waveforms of grid voltage  $u_g$ , output current  $i_L$ , voltage  $u_{1N}$ , and voltage  $u_{2N}$  at the grid-frequency scale. The waveforms at the switching-frequency scale in the positive and negative half-cycles are depicted in Fig. 11(b) and (c), respectively. From  $2u_{CM} = u_{1N} + u_{2N}$ , it can be observed that IZSL-H6 has a constant CM voltage, which is consistent with

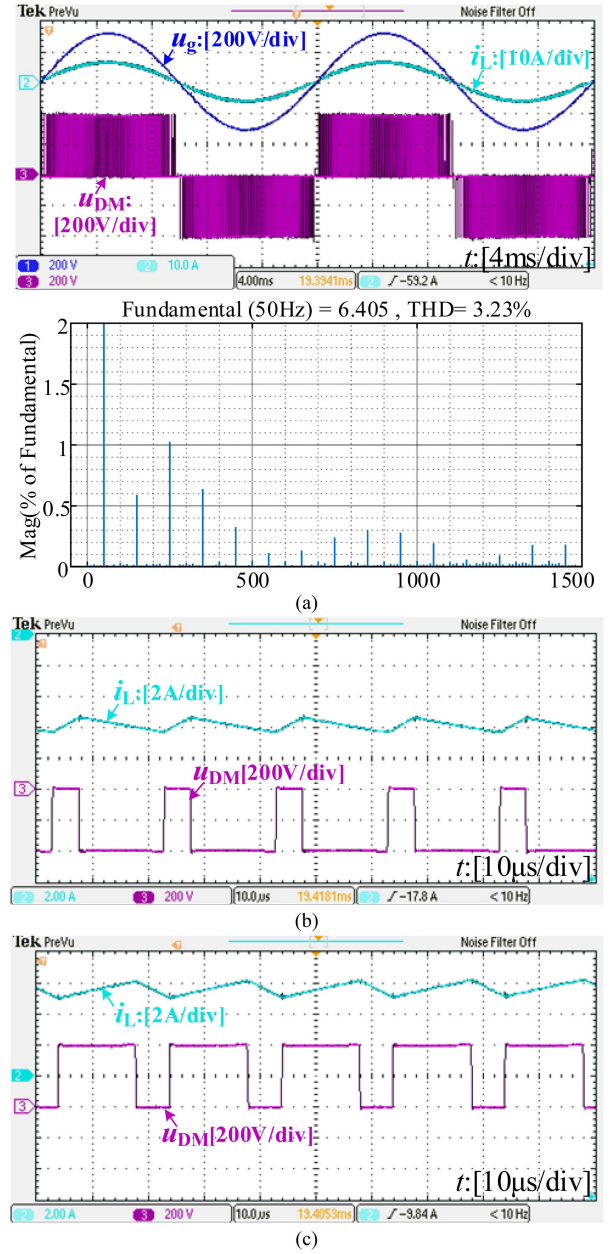


Fig. 10. Experimental waveforms of the grid voltage, the grid current, and the DM voltage. (a) DM voltage at the grid-frequency scale and FFT analysis result ( $u_g$  and  $u_{DM}$ : 200 V/div,  $i_L$ : 10 A/div, and time: 4 ms/div). (b) DM voltage in the positive half-cycle at the switching-frequency scale ( $i_L$ : 2 A/div, time: 10  $\mu$ s/div). (c) DM voltage in the negative half-cycle at the switching-frequency scale.

the theoretical analysis in Section III-B. Therefore, IZSL-H6 has an excellent LC suppression function.

### C. Verification of the Soft-Switching Performance

Fig. 12 shows the experimental waveforms of the gate driving voltage  $u_{GS5}$ ,  $u_{GS5a}$ , resonant voltage  $u_{C5a}$ , and resonant current  $i_{L5a}$ . It can be observed that the resonance tank operates normally when  $S_{5a}$  is turned ON, and the amplitude of the voltage  $u_{C5a}$  is equal to the input voltage  $U_{PV}$ . The experimental results validate the principal analysis, as presented in Fig. 2(c).

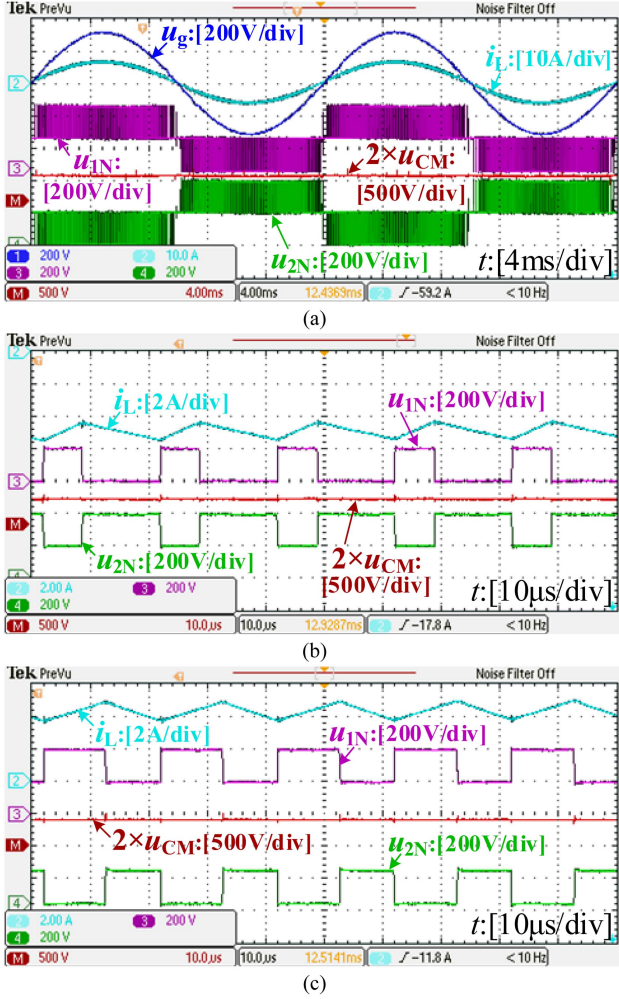


Fig. 11. Experimental waveforms of the grid voltage, the grid current, and the CM voltage. (a) DM voltage at the grid-frequency scale ( $u_g$  and  $u_{CM}$ : 200 V/div,  $i_L$ : 10 A/div, and time: 4 ms/div). (b) CM voltage in the positive half-cycle at the switching-frequency scale ( $i_L$ : 2 A/div, time: 10  $\mu$ s/div). (c) CM voltage in the negative half-cycle at the switching-frequency scale.

The experimental waveforms of  $u_{GS5}$ ,  $u_{GS5a}$ , voltage  $u_{S5}$ , and current  $i_{S5}$  of  $S_5$  at switching cycle are shown in Fig. 13(a). The current  $i_{S5}$  linearly increases after  $S_5$  is turned ON, achieving ZCS turn-ON for  $S_5$ , as shown in Fig. 13(b). After the current  $i_{S5}$  rises, there is no superposition of the sine resonant current, and it remains approximately constant. It means that only the output current flows through  $S_5$ . Fig. 13(c) shows that when the turn-OFF signal arrives,  $i_{S5}$  is already negative, thus achieving ZCS turn-OFF for  $S_5$ . In addition, the voltage stress  $u_{S5}$  is  $U_{PV}/2$ .

The experimental waveforms of  $u_{GS5}$ ,  $u_{GS5a}$ , voltage  $u_{S5a}$ , and current  $i_{S5a}$  of  $S_{5a}$  at switching cycle are shown in Fig. 14(a). Switch  $S_{5a}$  achieves ZCS turn-ON and turn-OFF due to carrying the resonant current of half a resonant cycle, as shown in Fig. 14(b) and (c). Because of the resonance action between the resonant inductor and the parasitic capacitor of the power device, a voltage spike appears in the voltage  $u_{S5a}$  during the switching state, and the voltage amplitude does not exceed the input voltage  $U_{PV}$ . After reaching stability,  $u_{S5a}$  stabilized at  $U_{PV}/2$ . Fig. 15(a) shows the voltage and current waveforms

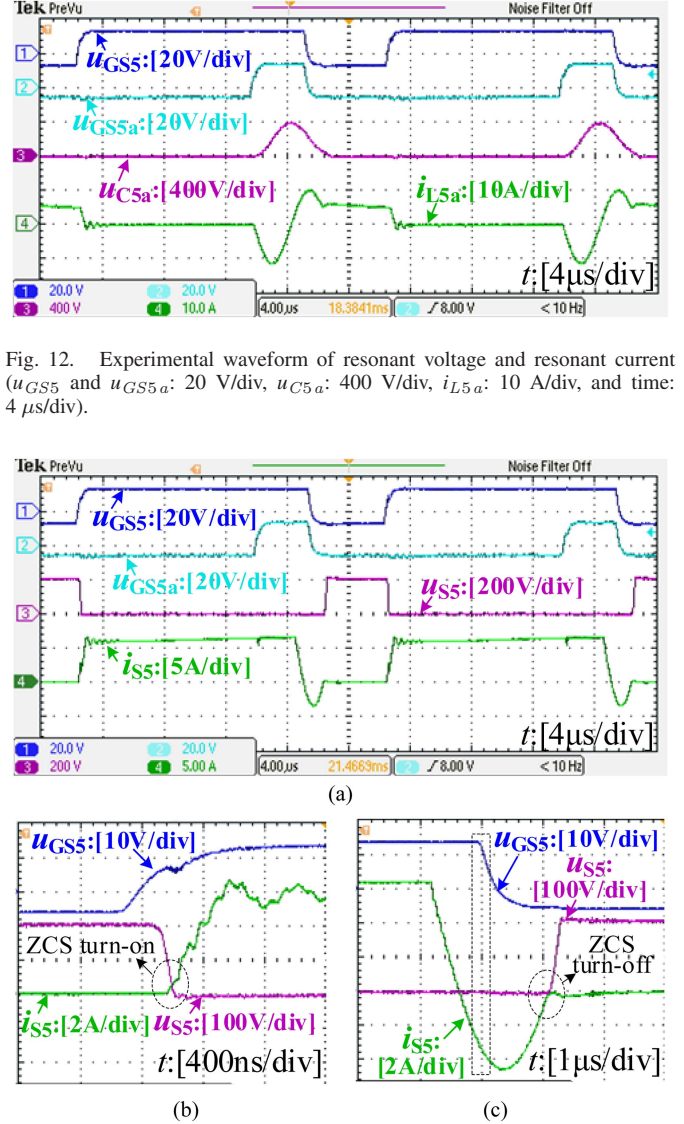


Fig. 12. Experimental waveform of resonant voltage and resonant current ( $u_{GS5}$  and  $u_{GS5a}$ : 20 V/div,  $u_{CSa}$ : 400 V/div,  $i_{L5a}$ : 10 A/div, and time: 4  $\mu$ s/div).

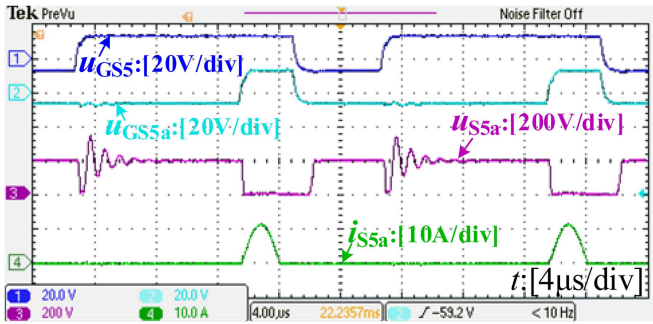
Fig. 13. Experimental waveforms of high-frequency main switch  $S_5$ . (a) Voltage and current waveforms of  $S_5$  at switching cycle ( $u_{GS5}$  and  $u_{GS5a}$ : 20 V/div,  $u_{S5}$ : 200 V/div,  $i_{S5}$ : 5 A/div, and time: 4  $\mu$ s/div). (b)  $S_5$  achieves ZCS turn-ON ( $u_{GS5}$ : 10 V/div,  $u_{S5}$ : 100 V/div,  $i_{S5}$ : 2 A/div, and time: 400 ns/div). (c)  $S_5$  achieves ZCS turn-OFF ( $u_{GS5}$ : 10 V/div,  $u_{S5}$ : 100 V/div,  $i_{S5}$ : 2 A/div, and time: 1  $\mu$ s/div).

of  $u_{GS5}$ ,  $u_{GS5a}$ , voltage  $u_{Da1}$ , and current  $i_{Da1}$  of  $D_{a1}$  at switching cycle. After the current  $i_{Da1}$  drops to zero, the voltage  $u_{Da1}$  remains at zero, achieving ZCS turn-OFF for  $D_{a1}$  and significantly mitigating the reverse recovery issue, as shown in Fig. 15(b).

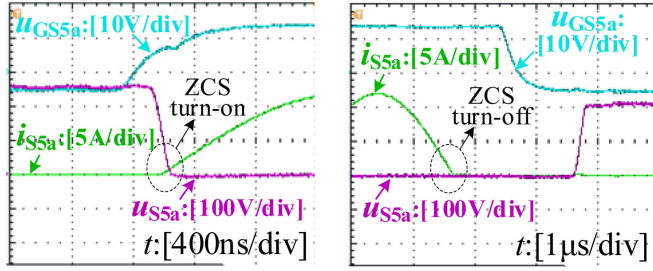
The experimental waveforms of  $u_{GS5}$ ,  $u_{GS5a}$ , the voltage  $u_{Df1}$ , and the current  $i_{Df1}$  of the freewheeling diode  $D_{f1}$  are shown in Fig. 16(a). Fig. 16(b) shows that the current  $i_{Df1}$  decreases linearly to zero, enabling  $D_{f1}$  to achieve ZCS turn-OFF and effectively mitigating the reverse recovery issue.

#### D. Verification of the Dynamic Performance

The dynamic response waveforms of the IZSL-H6 inverter are shown in Fig. 17 when the output current  $i_L$  rises and drops



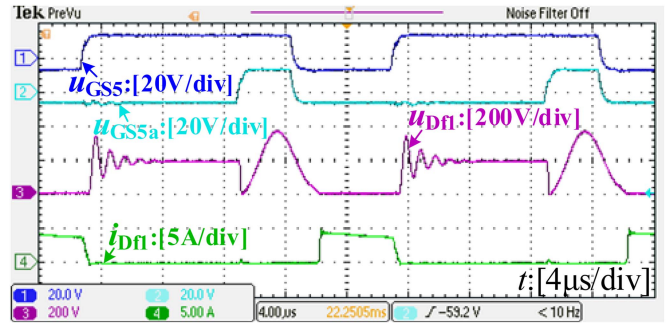
(a)



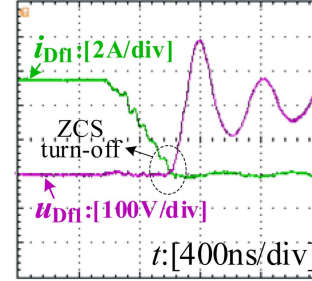
(b)

(c)

Fig. 14. Experimental waveforms of auxiliary switch  $S_{5a}$ . (a) Voltage and current waveforms of  $S_{5a}$  at switching cycle ( $u_{GS5}$  and  $u_{GS5a}$ : 20 V/div,  $u_{S5a}$ : 200 V/div,  $i_{S5a}$ : 10 A/div, and time: 4  $\mu$ s/div), (b)  $S_{5a}$  achieves ZCS turn-ON ( $u_{GS5a}$ : 10 V/div,  $u_{S5a}$ : 100 V/div,  $i_{S5a}$ : 5 A/div, and time: 400 ns/div), (c)  $S_{5a}$  achieves ZCS turn-OFF ( $u_{GS5a}$ : 10 V/div,  $u_{S5a}$ : 100 V/div,  $i_{S5a}$ : 5 A/div, and time: 1  $\mu$ s/div).

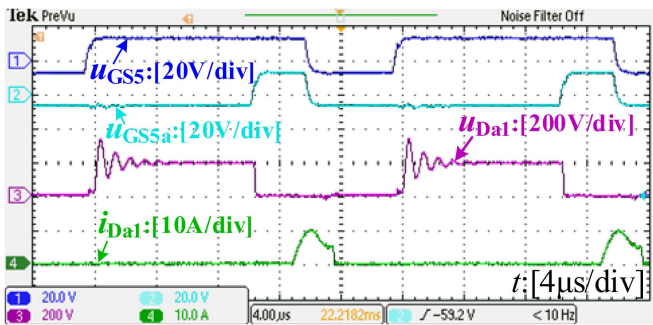


(a)

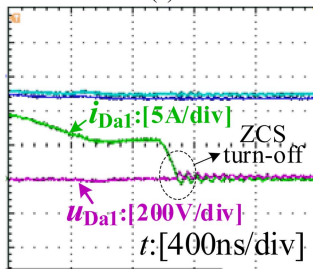


(b)

Fig. 16. Experimental waveforms of freewheeling diode  $D_{f1}$ . (a) Voltage and current waveforms of  $D_{f1}$  ( $u_{GS5}$  and  $u_{GS5a}$ : 20 V/div,  $u_{Df1}$ : 200 V/div,  $i_{Df1}$ : 5 A/div, and time: 4  $\mu$ s/div). (b)  $D_{f1}$  achieves ZCS turn-OFF ( $u_{Df1}$ : 100 V/div,  $i_{Df1}$ : 2 A/div, and time: 400 ns/div).

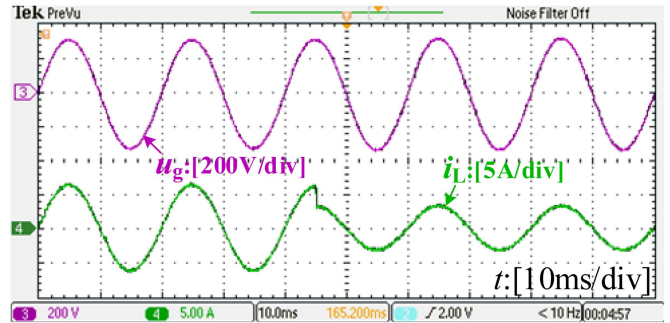


(a)

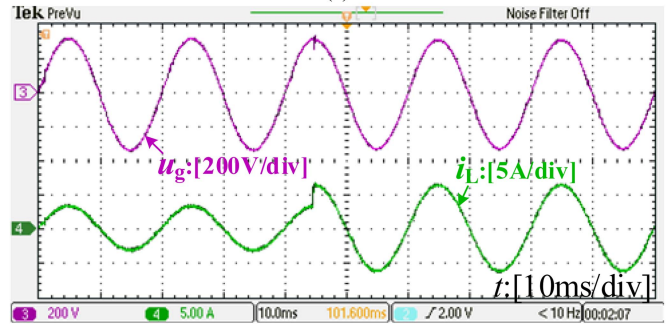


(b)

Fig. 15. Experimental waveforms of auxiliary diode  $D_{a1}$ . (a) Voltage and current waveforms of  $S_{5a}$  ( $u_{GS5}$  and  $u_{GS5a}$ : 20 V/div,  $u_{Da1}$ : 200 V/div,  $i_{Da1}$ : 10 A/div, and time: 4  $\mu$ s/div). (b)  $D_{a1}$  achieves ZCS turn-OFF ( $u_{Da1}$ : 100 V/div,  $i_{Da1}$ : 5 A/div, and time: 400 ns/div).



(a)



(b)

Fig. 17. Dynamic response of output current  $i_L$ . (a)  $i_L$  drops from full-load to half-load ( $u_g$ : 200 V/div,  $i_L$ : 5 A/div, and time: 4 ms/div). (b)  $i_L$  rises from half-load to full-load.

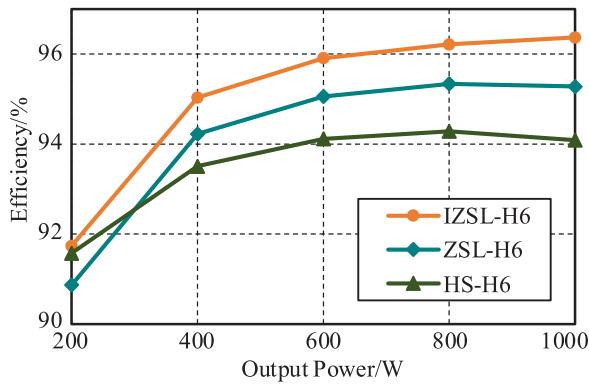


Fig. 18. Efficiency curves comparison among the IZSL-H6, ZSL-H6 [35], and HS-H6 [17].

suddenly. It can be seen that during the sudden switch between full-load and half-load, IZSL-H6 represents good dynamic performance, as shown in Fig. 17(a) and (b).

Fig. 18 illustrates the efficiency curves comparison among HS-H6, IZSL-H6, and ZSL-H6 at different output powers to validate the efficiency advantages of the proposed IZSL-H6. It can be observed that the efficiency of IZSL-H6 and HS-H6 is similar and slightly higher than ZSL-H6 when the output power is 200 W. As the output power increases, the efficiency of IZSL-H6 and ZSL-H6 is higher than HS-H6. The efficiency of IZSL-H6 at full-load is 96.37%, which is 1.09% higher than ZSL-H6. In summary, within the full power range, the efficiency of IZSL-H6 is higher than ZSL-H6.

## VI. CONCLUSION

An improved ZSL inverter with low conduction loss has been proposed in this article. Several clear merits are summarized as follows.

- 1) All power devices in the proposed IZSL-H6 feature zero-current turn-ON and turn-OFF, achieving ZSL and eliminating diode reverse recovery issues.
- 2) The excellent LC suppression performance of IZSL-H6 has been demonstrated, as the CM voltage remains constant under unipolar SPWM control.
- 3) The resonance tanks and the main power loops are separated in the proposed IZSL-H6. Compared with ZSL-H6, the current amplitude of the main switches in IZSL-H6 is reduced to the output current from twice the output current. In addition, IZSL-H6 reduces the number of power devices through which resonant current flows and reduces conduction loss.

These advantages were validated through experimentation with a 1000-W IZSL-H6 prototype. The results indicate that the proposed improved ZSL inverter is suitable for transformerless PV generation systems.

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