

Syntheses of Three-Port DC–DC Converters

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Abstract—This article proposes a systematic method to construct three-port converters (TPCs) and bidirectional three-port converters (BTPCs) by integrating two dc–dc converters including non-isolated and isolated types. By adding extra one power switch and one diode, the TPCs can be constructed by the dc–dc converters. A series of the proposed TPCs can provide independent power flow control of single-input to single-output, single-input to dual-output, and dual-input to single-output. By adding extra two power switches, the BTPCs can be constructed by the dc–dc converters. The power flows between any two ports can be controlled bidirectionally without significantly altering their architecture. Finally, a typical nonisolated BTPC is analyzed and implemented with rated power of 300 W and three ports voltages of 48, 72, and 200 V to verify the feasibility and effectiveness of the theoretical analyses. The highest measured efficiency is 98.4%.

Index Terms—Bidirectional converter, energy storage, renewable energy, three-port converter (TPC).

I. INTRODUCTION

THREE-PORT converters (TPCs) have recently gained popularity in sustainable energy system (SUS), such as wind power and solar power, and energy storage system (ESS), which can ensure a continuous and stable power supply for the load [1], [2], [3], [4], [5], [6], [7], [8], [9], [10], [11], [12], [13], [14], [15], as shown in Fig. 1(a). For multiple ESSs applications, the bidirectional power flows among ESSs and dc bus are required, as shown in Fig. 1(b) [16], [17], [18], [19], [20], [21], [22], [23], [24], [25], [26], [27], [28], [29], [30], [31]. Traditionally, three independent unidirectional dc–dc converters are employed to interface source port V_S , battery port V_B , and load port V_L , as shown in Fig. 2. However, components cannot be shared among three ports, resulting in high cost and low efficiency. To address the problem, many researches on TPCs have been done regarding topology derivations for various applications.

Based on coupled inductor and voltage double techniques, the nonisolated TPCs have been presented [2], [3]. However, it

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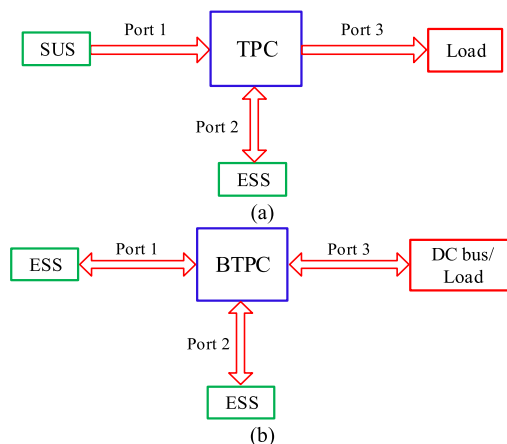


Fig. 1. Applications of (a) TPC in SUS and ESS and (b) BTPC in multiple ESSs.

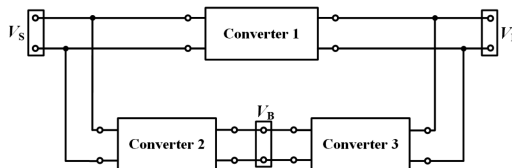


Fig. 2. Conventional SUS and ESS systems with three converters.

suffers from the cross-regulation problem with multiple power flow conditions. By using three inductors, the power flows of the single-input–dual-output (SIDO) modes can be controlled independently, thus the cross regulation problem is solved [4]. By integrating a coupled inductor with three power switches, the boost-flyback and switched-capacitor techniques are used to transfer energy from photovoltaic (PV) to output and battery to output, respectively [5]. However, the power flows from PV to battery and load are coupled. TPC can also be constructed by integrating switched capacitor converter, bidirectional pulsewidth modulation (PWM) converter, and series-resonant converter, but more power switches and complex control are used [6]. The number of power switches was reduced by integrating a bidirectional converter for TPC [7]. For dual-input sources operation, the quadratic boost technique is used to form a TPC with reduced device counts to achieve high stepup [8]. However, the control is complex.

For safety requirements, the multiple windings with galvanic isolation transformer are used for isolated TPC. Isolated TPCs with high-power capacity was presented based on dual active bridge with a third winding and rectifier output, but

more power switches are used [9]. Isolated TPC with simple control scheme was composed of a Z-source boost converter and coupled inductor with voltage doubler, but more components are used and full-load efficiency is low [10]. By integrating boost and dual switches buck–boost converters [11], interleaved boost converter [12], and switched-capacitor technology [13] with LLC converter, isolated TPCs can achieve higher efficiency; however, the power managements among three ports become complex. The single magnetic core isolated TPC was formed by integrating bidirectional PWM converter and SRC, but the energy from battery to output needs twice power transferring processes [14]. Isolated TPC was presented with two interleaved flyback–forward converters; however, the power flow control in SIDO is complex [15]. By integrating full-bridge cell with a three-winding transformer [16], [17], [18] and a boost converter [19], isolated TPCs were presented with more power switches and complex control.

In combining a full-bridge inverter, a conventional boost, and a bidirectional single inductor converter, a nonisolated bidirectional three-port converter (BTPC) was presented [21]. A simple nonisolated BTPC composed of a boost converter and a bidirectional buck/boost converter with two power switches and two inductors was presented, but the energy from PV to battery needs twice power transferring processes [22].

With four power switches, the nonisolated BTPCs can be formed by two conventional bidirectional buck–boost converters in parallel or in series; however, twice power transferrings are required for the energy transferings between the battery and dc bus, and from PV to battery, respectively, [23]. Two nonisolated BTPCs can be constructed by integrating two bidirectional buck–boost converters [24] or two bidirectional buck converters [25]. However, the time-multiplexing control scheme in SIDO stage is required. Four phase bidirectional buck–boost with coupled inductor was presented [26]. But more power switches are adopted.

Isolated BTPCs can be built by integrated three full-bridge cells with one transformer [27], [28], [29], [30]. However, more power switches are used and control scheme is complicated. By using the boost flyback, and forward converters, an isolated BTPC was formed by sharing the power switches [31]. However, it is difficult to control power flows independently among two batteries and load.

The simple syntheses of the nonisolated TPCs were presented by adding one power switch and one diode in between two sources with two conventional converters [32]. By an additional one power switch and one diode with the conventional converter, the nonisolated TPC was revealed [33]. The syntheses of integrating SIDO converters, dual-input–single-output (DISO) dc–dc converters, and converters with single inductor for multiple-input and multiple-output were revealed [34], [35], [36], [37]. However, the energy transferings between source(s) and load(s) are unidirectional. By integrating two power switches and inductor/transformer, the bidirectional nonisolated converter for battery port and unidirectional isolated converter for load were addressed [38]. A family of BTPCs was presented by adding two bidirectional buck–boost converters with cascaded structure [39].

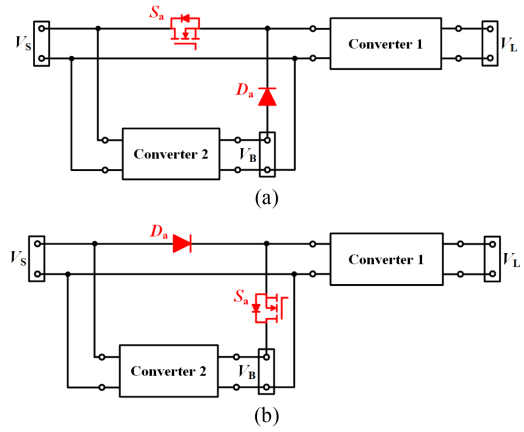


Fig. 3. Topology syntheses for constructing TPCs. (a) Integrate TPC under $V_S > V_B$. (b) Integrate TPC under $V_S < V_B$.

In this article, TPCs are derived systematically by adding additional one power switch and one diode. The power flows of the constructed TPCs are controlled independently from SUS to ESS/load and ESS to load. Also, by adding two power switches in connecting two dc–dc converters, BTPCs are formed analytically. The power flows among SUS, ESS, and dc bus can be controlled independently by the presented BTPCs. These TPCs and BTCs are needed to attain suitable operation ranges for different voltage applications in power systems.

II. SYNTHESSES AND TOPOLOGY DERIVATIONS OF TPCs AND BTPCs

To integrate a TPC with two converters, additional power switch S_a and diode D_a are used to achieve power flows, as shown in Fig. 3. To avoid the shorted circuit of source and battery, power switch S_a is connected to source and power diode D_a is connected to battery when $V_S > V_B$ as shown in Fig. 3(a). When $V_S < V_B$, power diode D_a is connected to source and power switch S_a is connected to battery as shown in Fig. 3(b).

By replacing the diode with power switch in Fig. 3, the bidirectional power flows can be performed. Nonisolated BTPCs and isolated BTPCs composed of two battery ports V_{B1} and V_{B2} , and a dc-bus port V_{Bus} can be derived by combing the two bidirectional converters with two additional power switches, as shown in Fig. 4. When $V_{B1} > V_{B2}$, drain terminal of S_{a1} is connected to V_{B1} , source terminal of S_{a2} is connected to V_{B2} , and source terminal of S_{a1} and drain terminal of S_{a2} are common connected to converter 2. When $V_{B2} > V_{B1}$, source terminal of S_{a1} is connected to V_{B1} , drain terminal of S_{a2} is connected to V_{B2} , and drain terminal of S_{a1} and source terminal of S_{a2} are common connected to converter 2. By setting ON/OFF of S_{a1} and S_{a2} , the energy transfers from V_{B1} to V_{Bus} and V_{B2} to V_{Bus} can be controlled independently, as shown in Fig. 4(a) and (b). The voltage stress on power switches S_{a1} and S_{a2} is $|V_{B1} - V_{B2}|$. In order to keep the two port voltages of converters with the same reference point in Figs. 3 and 4, converter 2 must be common ground.

In order to illustrate the synthesis of TPC, based on the five basic converters, namely buck, boost, buck–boost, flyback, and

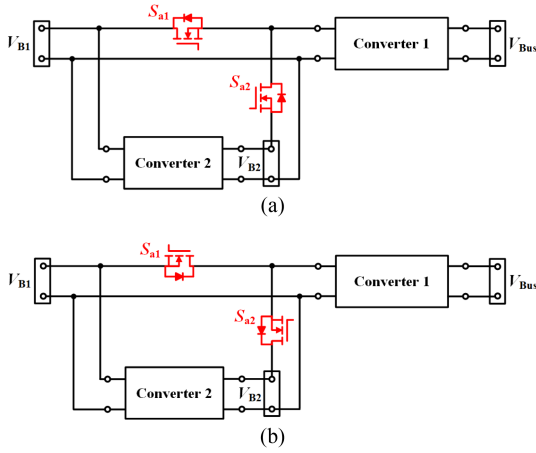


Fig. 4. Topology syntheses for constructing BTPCs. (a) Integrate BTPC under $V_{B1} > V_{B2}$. (b) Integrate BTPC under $V_{B1} < V_{B2}$.

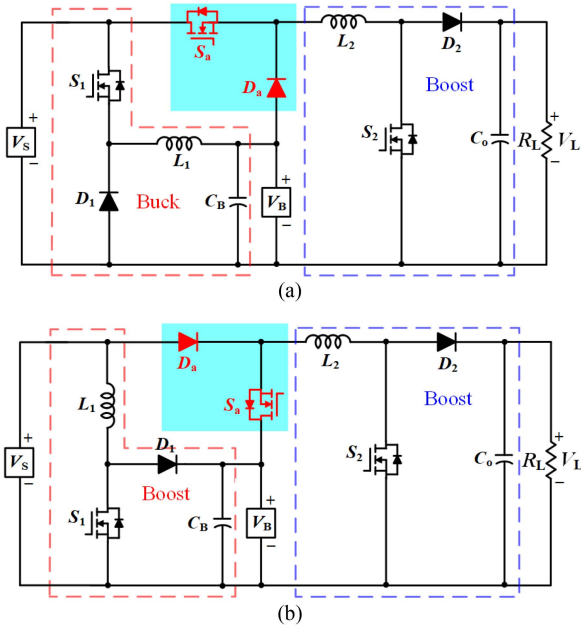


Fig. 5. Nonisolated TPCs under (a) $V_L > V_S > V_B$ (buck + boost) and (b) $V_L > V_B > V_S$ (boost + boost).

forward, nonisolated TPCs and isolated TPCs can be derived by combing the two basic converters.

Nonisolated TPCs: When $V_L > V_S > V_B$, buck converter and boost converter are used to construct TPC. The buck converter is used to transfer energy from V_S to V_B , and the boost converter is used to provide energy to load from source and battery as shown in Fig. 5(a). When V_S provides energy to V_L , additional power switch S_a , is always ON and additional diode D_a is used to avoid shorted circuit of V_S and V_B . When V_B provides energy to V_L , additional power switch S_a is always OFF to block the energy from V_S to V_L . Then, the energy transferring from either V_S or V_B to V_L can be controlled independently. When V_S provides energy to V_B and V_L , additional power switch S_a is always ON, and S_1 and S_2 are controlled independently to regulate the power from V_S to V_B and V_L , respectively. When $V_L > V_B > V_S$, two

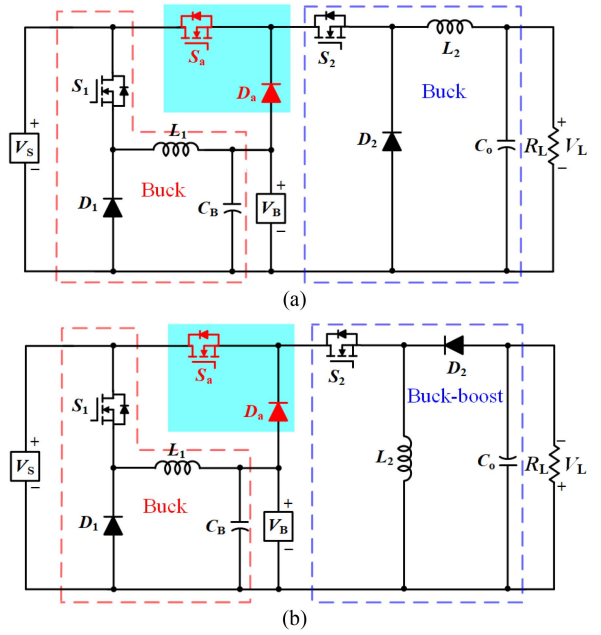


Fig. 6. Under $V_S > V_B$, two integrated nonisolated TPCs with (a) buck + buck and (b) buck + buck boost.

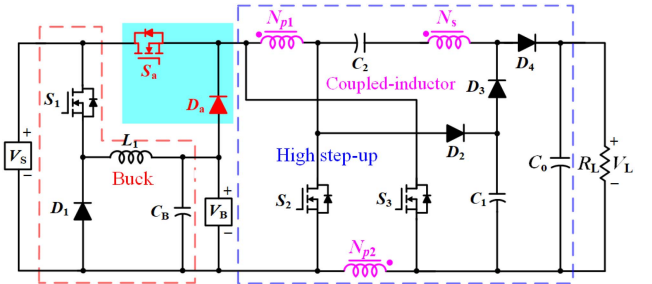


Fig. 7. One integrated nonisolated TPCs with buck converter and high-step-up converter.

boost converters are used to convert energy from V_S to V_B , V_B to V_L , and V_S to V_L , as shown in Fig. 5(b). When only V_S provides energy to V_L , S_a is always OFF. S_a is always ON when only V_B provides energy to V_L . Since $V_B > V_S$, the OFF/ON of S_a and diode D_a are used to ensure that there is only one source providing energy to V_L independently.

Similarly, as shown in Fig. 6(a), when $V_S > V_B > V_L$, two buck converters are used to construct TPC with additional power switch and diode. When $V_S > V_B$, one buck converter and one buck-boost converter are used to convert energy among V_S , V_B , and V_L , as shown in Fig. 6(b).

To demonstrate the generality of the proposed topology synthesis, in Fig. 5(a), by replacing the boost converter with high step-up converter in [40], a nonisolated TPC with high-voltage gain is shown in Fig. 7. Assuming the winding ratios of N_{p1} , N_{p2} , and N_s of the coupled inductor are 1 : 1 : n , and D is the duty cycle of synchronous switches S_2 and S_3 , the voltage gain from V_S or V_B to V_L is written as

$$\frac{V_L}{V_S} = \frac{3 + n + D}{1 - D} \quad \text{or} \quad \frac{V_L}{V_B} = \frac{3 + n + D}{1 - D}. \quad (1)$$

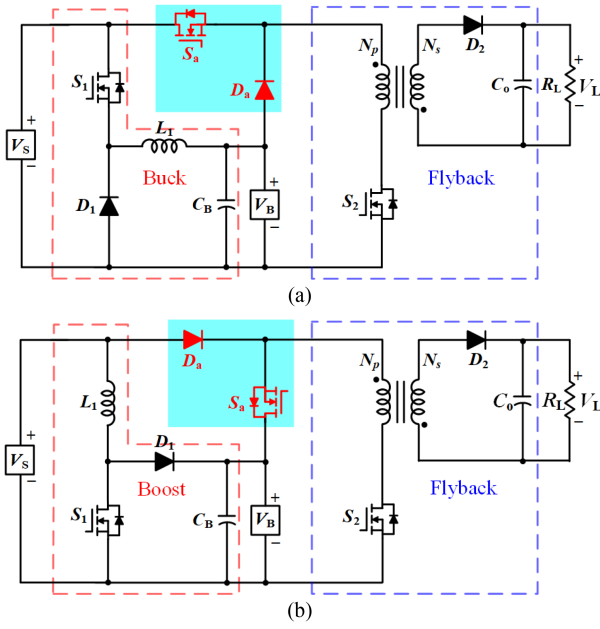


Fig. 8. Isolated TPCs under (a) $V_S > V_B$ (buck + flyback) and (b) $V_S < V_B$ (boost + flyback).

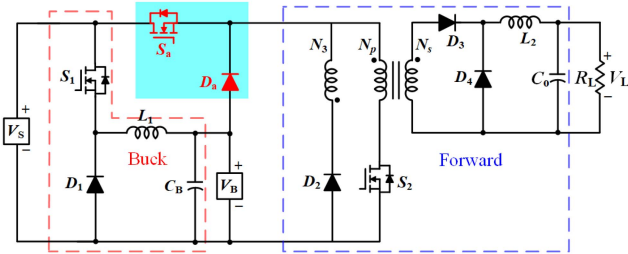


Fig. 9. Isolated TPC with buck and forward converters under $V_S > V_B$.

Isolated TPCs: When $V_S > V_B$, buck converter and flyback converter are used to construct isolated TPC. The buck converter is used to transfer energy from V_S to V_B . As shown in Fig. 8(a), the flyback converter is used to provide energy to load from V_S and V_B by controlling power switch S_a always ON and OFF, respectively. Then, the energy transferring from either V_S or V_B to V_L can be controlled independently. When V_S provides energy to V_B and V_L , power switch S_a is always ON, and S_1 and S_2 are controlled independently to regulate the power from V_S to V_B and V_S to V_L , respectively.

Similarly, when $V_S < V_B$, the boost converter is used to convert energy from V_S to V_B , and the flyback converter is used to convert energy from V_S to V_L and V_B to V_L , as shown in Fig. 8(b). The power transferrings among V_L , V_B , and V_S are controlled independently. By the same concept, the forward converter can also be adopted for the energy transfers from V_S to V_L and V_B to V_L , as shown in Fig. 9.

Based on Fig. 3, integrating a buck converter and an isolated soft-switching high-step-up converter in [41], an isolated TPC is shown in Fig. 10. From V_S or V_B to V_L , S_2 and S_3 can achieve zero-voltage switching.

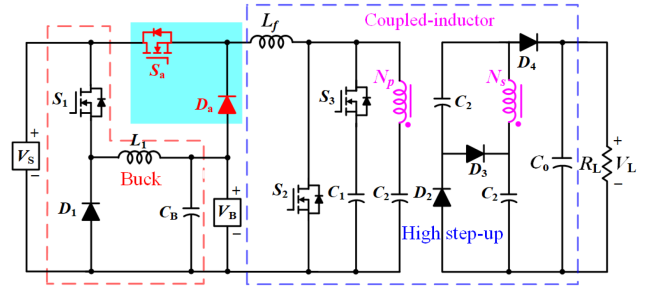


Fig. 10. One integrated isolated TPCs with buck converter and soft-switching high step-up converter $V_S > V_B$.

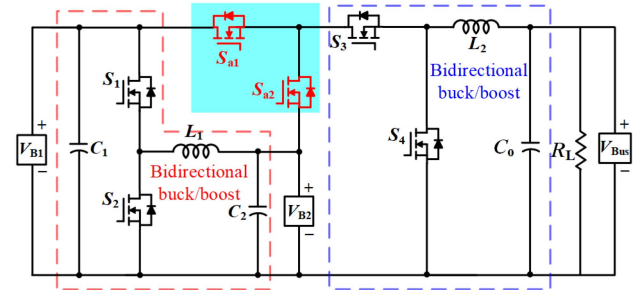


Fig. 11. Nonisolated BTPC with bidirectional buck/boost and buck/boost converters under $V_{B1} > V_{B2} > V_{BUS}$.

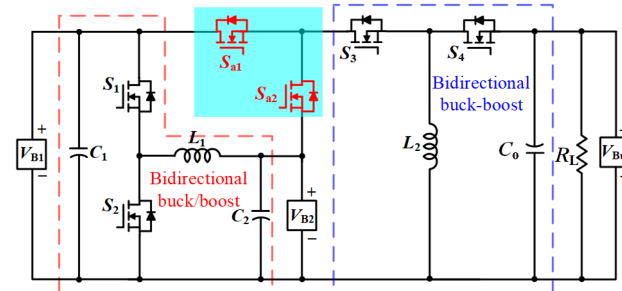


Fig. 12. Nonisolated BTPC with bidirectional buck/boost and buck-boost converters under $V_{B1} > V_{B2}$.

Nonisolated BTPCs: When $V_{B1} > V_{B2} > V_{BUS}$, two bidirectional buck/boost converters are used to construct BTPC, as shown in Fig. 11. The bidirectional buck/boost converter constructed by S_1 , S_2 , and L_1 is used to transfer energy between V_{B1} and V_{B2} while S_{a1} and S_{a2} are always OFF. By setting ON/OFF of S_{a1} and S_{a2} , the bidirectional buck/boost converter constructed by S_3 , S_4 , and L_2 is used to transfer energy between V_{B1} and V_{BUS} , and V_{B2} and V_{BUS} . When energy is transferred between V_{B1} and V_{BUS} , power switch S_{a1} is always OFF to block the energy from V_{B1} to V_{BUS} . When energy is transferred between V_{B1} and V_{BUS} , power switch S_{a2} is always OFF to avoid shorted circuit of V_{B1} and V_{B2} , and also block the energy from V_{BUS} to V_{B2} . Then, the power transferring among V_{B1} , V_{B2} , and V_{BUS} are controlled independently.

Similarly, as shown in Fig. 12, when $V_{B1} > V_{B2}$, one bidirectional buck/boost converter and one bidirectional buck-boost converters are used to construct BTPC with two additional power switches.

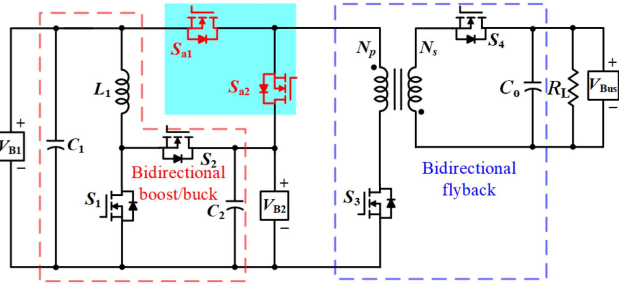


Fig. 13. Isolated BTPC with bidirectional boost/buck and flyback converters under $V_{B1} > V_{B2}$.

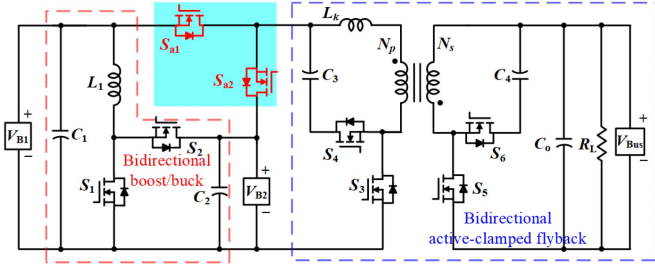


Fig. 14. Isolated BTPC with bidirectional boost/buck and active-clamped flyback converters under $V_{B1} > V_{B2}$.

Isolated BTPCs: When $V_{B2} > V_{B1}$, bidirectional boost/buck converter and bidirectional flyback converter are used to construct BTPC, as shown in Fig. 13.

When energy is transferred between V_{B1} and V_{B2} , power switches S_{a1} and S_{a2} are always OFF to avoid energy transfers between V_{B1} and V_{BUS} , and V_{B2} and V_{BUS} . The bidirectional flyback converter is used to transfer energy between V_{B1} and V_{BUS} , power switch S_{a1} is always ON and S_{a2} is always OFF. When energy is transferred between V_{B2} and V_{BUS} by the bidirectional flyback converter, power switch S_{a1} is always OFF and S_{a2} is always ON to block the energy transfer between V_{B1} and V_{BUS} . Then, the power transferrings among V_{B1} , V_{B2} , and V_{BUS} are controlled independently. Moreover, integrating a bidirectional boost/buck converter and a bidirectional active-clamped flyback converter in [42], an isolated BTPC is presented in Fig. 14. V_{B1} and V_{B2} are isolated from V_{BUS} . Since the power switches can achieve soft-switching when the energy is transferred with V_{BUS} , the switching frequency can be increased for reducing the transformer size.

III. ANALYSES AND DESIGN OF NONISOLATED BTPC

The BTPC composed of bidirectional buck/boost converter and boost/buck converter is analyzed and designed to build the experimental prototype for verification of the proposed synthesis method, as shown in Fig. 15. Where additional switches S_{a1} and S_{a2} are added to form the bidirectional energy transfers between V_{B1} and V_{B2} , V_{B1} and V_{BUS} , and V_{B2} and V_{BUS} . To simply the analyses, the following conditions are assumed.

- 1) MOSFETs are ideal, except the body diode of MOSFETs is considered.

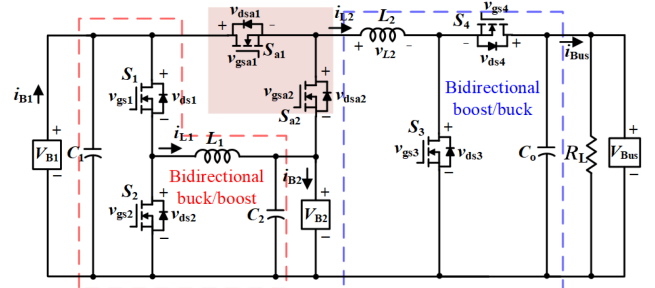


Fig. 15. Nonisolated BTPC with bidirectional buck/boost and boost/buck converters under $V_{BUS} > V_{B1} > V_{B2}$.

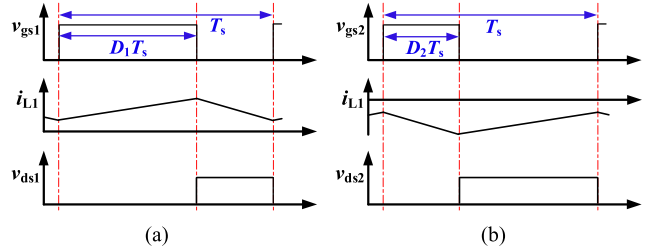


Fig. 16. Key waveforms for Stage I. (a) V_{B1} to V_{B2} (buck). (b) V_{B2} to V_{B1} (boost).

- 2) The proposed converter is operated at steady state under continuous conduction mode (CCM) conditions.
- 3) The voltages of the three ports are defined as $V_{BUS} > V_{B1} > V_{B2}$.
- 4) D_1 , D_2 , D_3 , and D_4 are defined as the duty ratios of S_1 , S_2 , S_3 , and S_4 , respectively.

Five stages are discussed in the following sections.

A. Stage I: Power Flows Between V_{B1} and V_{B2} ($P_{B1} = P_{B2}$)

In this stage, switches S_{a1} , S_{a2} , S_3 , and S_4 are OFF. The bidirectional buck/boost converter is used to transfer the energy between V_{B1} and V_{B2} , with key waveforms, as shown in Fig. 16. S_1 and S_2 act as the main switch when V_{B1} provides energy to V_{B2} with buck converter, and V_{B2} provides energy to V_{B1} with boost converter, respectively. Then, the voltage conversion ratios can be derived as follows:

$$V_{B2} = D_1 V_{B1}. \quad (2)$$

$$V_{B1} = \frac{1}{1 - D_2} V_{B2}. \quad (3)$$

B. Stage II: Power Flows Between V_{B1} and V_{BUS} ($P_{B1} = P_{BUS}$)

In this stage, switches S_1 , S_2 , and S_{a2} are turned OFF. The bidirectional boost/buck converter is used to transfer the energy between V_{B1} and V_{BUS} , with key waveforms, as shown in Fig. 17. S_3 and S_4 act as the main switch when V_{B1} provides energy to V_{BUS} with boost converter, and V_{BUS} provides energy to V_{B1} with buck converter, respectively. Then, the voltage conversion

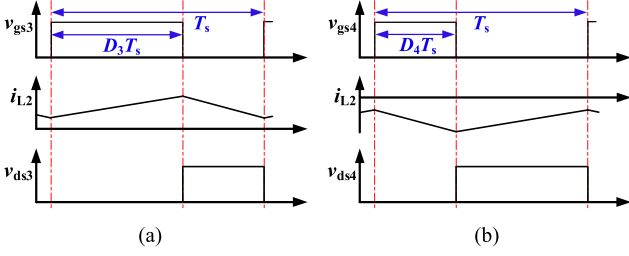


Fig. 17. Key waveforms for Stage II. (a) V_{B1} to V_{Bus} (boost). (b) V_{Bus} to V_{B1} (buck).

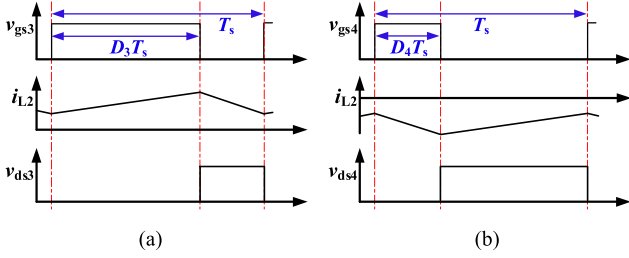


Fig. 18. Key waveforms for Stage III. (a) V_{B2} to V_{Bus} (boost). (b) V_{Bus} to V_{B2} (buck).

ratios can be derived as follows:

$$V_{Bus} = \frac{1}{1 - D_3} V_{B1} \quad (4)$$

$$V_{B1} = D_4 V_{Bus}. \quad (5)$$

C. Stage III: Power Flows Between V_{B2} and V_{Bus} ($P_{B2} = P_{Bus}$)

In this stage, S_1 , S_2 , and S_{a1} are turned OFF. The bidirectional boost/buck converter is used to transfer the energy between V_{B2} and V_{Bus} , with key waveforms, as shown in Fig. 18. S_3 and S_4 act as the main switch when V_{B2} provides energy to V_{Bus} with boost converter, and V_{Bus} provides energy to V_{B2} with buck converter, respectively. Then, the voltage conversion ratios can be derived as follows:

$$V_{Bus} = \frac{1}{1 - D_3} V_{B2} \quad (6)$$

$$V_{B2} = D_4 V_{Bus}. \quad (7)$$

D. Stage IV: Power Flows From V_{B2} to V_{B1} and V_{Bus} ($P_{B2} = P_{B1} + P_{Bus}$)

In this stage, V_{B2} simultaneously provides energy to V_{B1} and V_{Bus} . S_{a2} is always turned ON, and S_{a1} is always turned OFF. S_2 and S_3 are the main switches regulating the power from V_{B2} to V_{B1} and from V_{B2} to V_{Bus} , respectively. There is no energy transfer between V_{B1} and V_{Bus} . Thus, it can transfer energy from one input to two outputs with independent power flow control. The relationships between V_{B2} and V_{B1} , V_{Bus} are the same as (3) and (6).

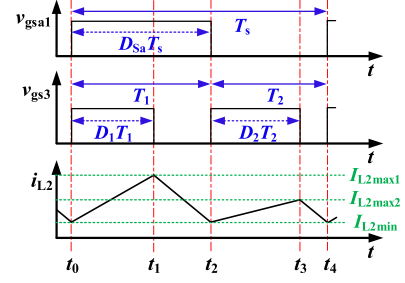


Fig. 19. Key waveforms from V_{B1} and V_{B2} to V_{Bus} .

E. Stage V: Power Flows From V_{B1} and V_{B2} to V_{Bus}

($P_{B2} + P_{B1} = P_{Bus}$)

In this stage, switches S_1 and S_2 are always turned OFF, and S_{a1} and S_3 are the main switches. Combing power flows from V_{B1} to V_{Bus} and V_{B2} to V_{Bus} , and applying interleaved control methods, V_{B1} and V_{B2} transfer energy to V_{Bus} independently, as shown in Fig. 19. From moments t_0 to t_2 , S_{a1} is ON and V_{B1} provides energy to V_{Bus} . From moments t_2 and t_4 , S_{a1} is OFF and V_{B2} provides energy to V_{Bus} .

Under CCM, in Fig. 19, during $(1 - D_1)T_1$, the charge of L_2 is obtained as the following:

$$Q_1 = \frac{1}{2} (1 - D_1) T_1 \left[I_{L2min} + \left(\frac{V_{B1}}{L_2} D_1 T_1 + I_{L2min} \right) \right]. \quad (8)$$

Also, during $(1 - D_2)T_2$, the charge of L_2 is obtained as follows:

$$Q_2 = \frac{1}{2} (1 - D_2) T_2 \left[I_{L2min} + \left(\frac{V_{B2}}{L_2} D_2 T_2 + I_{L2min} \right) \right]. \quad (9)$$

During $0 - T_s$, by using charge balance of L_2 , the following can be derived:

$$Q_1 + Q_2 = I_{Bus} T_s \quad (10)$$

Substituting (8) and (9) into (10), I_{L2min} can be derived as

$$I_{L2min} = \frac{2I_{Bus}T_s - \frac{V_{B1}}{L_2} D_1 (1 - D_1) T_1^2 - \frac{V_{B2}}{L_2} D_2 (1 - D_2) T_2^2}{2(1 - D_1) T_1 + 2(1 - D_2) T_2}. \quad (11)$$

The average currents flowing through V_{B1} and V_{B2} are derived as follows:

$$I_{B1} = \frac{V_{B1}}{2L_2} D_1 T_1 + I_{L2min} \quad (12)$$

$$I_{B2} = \frac{V_{B2}}{2L_2} D_2 T_2 + I_{L2min}. \quad (13)$$

From (12) and (13), the ratio of the power from V_{B1} and V_{B2} can be obtained as follows:

$$\frac{P_{B1}}{P_{B2}} = \frac{V_{B1} I_{B1}}{V_{B2} I_{B2}} = \frac{V_{B1} \left(\frac{V_{B1}}{2L_2} D_1 T_1 + I_{L2min} \right)}{V_{B2} \left(\frac{V_{B2}}{2L_2} D_2 T_2 + I_{L2min} \right)}. \quad (14)$$

Substituting (11) into (14)

$$\frac{P_{B1}}{P_{B2}} = \frac{V_{B1} \left[\frac{V_{B1}}{2L_2} D_1 T_1 + \frac{2I_{Bus} T_S - \frac{V_{B1}}{L_2} D_1 (1-D_1) T_1^2 - \frac{V_{B2}}{L_2} D_2 (1-D_2) T_2^2}{2(1-D_1)T_1 + 2(1-D_2)T_2} \right]}{V_{B2} \left[\frac{V_{B2}}{2L_2} D_2 T_2 + \frac{2I_{Bus} T_S - \frac{V_{B1}}{L_2} D_1 (1-D_1) T_1^2 - \frac{V_{B2}}{L_2} D_2 (1-D_2) T_2^2}{2(1-D_1)T_1 + 2(1-D_2)T_2} \right]}. \quad (15)$$

From (15), the ratio of P_{B1} and P_{B2} is controlled by the magnitude of T_1 and T_2 . Thus, the energy of P_{B1} and P_{B2} is allocated to the output.

F. Key Component Design

The performance of the proposed converter is highly affected by the inductance of L_1 and L_2 . When V_{B2} provides energy to V_{B1} in stage I and by the charge balance rule, L_1 in boundary conduction mode (BCM) can be derived as follows:

$$L_1 = \frac{D_1 (1 - D_2) V_{B2}}{2I_{B1,BCM} f_s} \quad (16)$$

where $I_{B1,BCM}$ is the current with port V_{B1} under BCM.

Similarly, L_2 under BCM when V_{B1} provides energy to V_{Bus} in stage II can be derived as follows:

$$L_2 = \frac{D_3 (1 - D_3) V_{B1}}{2I_{Bus,BCM} f_s} \quad (17)$$

where $I_{Bus,BCM}$ is defined as the bus current under BCM.

The voltage stresses on the power switches in Stages I–III, are shown as follows:

$$V_{ds1} = V_{ds2} = V_{B1} \quad (\text{stage I}) \quad (18)$$

$$V_{dsa1} = V_{dsa2} = V_{B1} - V_{B2} \quad (\text{stage II}) \quad (19)$$

$$V_{ds3} = V_{ds4} = V_{Bus} \quad (\text{stage III}). \quad (20)$$

From V_{B2} to V_{B1} and V_{B2} to V_{Bus} , the maximum value of the current through L_1 and L_2 are, respectively, derived as the follows:

$$I_{L1max} = \frac{(1 - D_2) V_{B1} D_2}{2L_1 f_s} + \frac{|I_{B1}|}{1 - D_2} \quad (21)$$

$$I_{L2max} = \frac{(1 - D_3) V_{Bus} D_3}{2L_2 f_s} + \frac{I_{Bus}}{1 - D_3}. \quad (22)$$

The maximum current flowing through power switches S_1 , S_2 , S_3 , S_4 , and S_{a2} can be derived as

$$I_{S1max} = I_{S2max} = I_{L1max} \quad (23)$$

$$I_{Sa2max} = I_{S3max} = I_{S4max} = I_{L2max}. \quad (24)$$

From V_{B1} to V_{Bus} , the maximum current through S_{a1} is derived as

$$I_{Sa1max} = \frac{(1 - D_3) V_{Bus} D_3}{2L_2 f_s} + \frac{I_{Bus}}{1 - D_3}. \quad (25)$$

TABLE I
SYSTEM SPECIFICATIONS AND KEY COMPONENTS

| Parameters | Values |
|--|--|
| Voltage of Port 1 (V_{B1}) | 72 V |
| Voltage of Port 2 (V_{B2}) | 48 V |
| Voltage of Port 3 (V_{Bus}) | 200 V |
| Rated Power of Port 1 (P_{B1}) | 300 W |
| Rated Power of Port 2 (P_{B2}) | 300 W |
| Rated Power of Port 3 (P_{Bus}) | 300 W |
| Switching Frequency (f_s) | 50 kHz |
| Inductances (L_1, L_2) | L_1 : 130 μ H L_2 : 555 μ H |
| Power MOSFETs (S_1, S_2, S_{a1}, S_{a2}) | IPP110N20N3 |
| Power MOSFETs (S_3, S_4) | SCT3080AL |

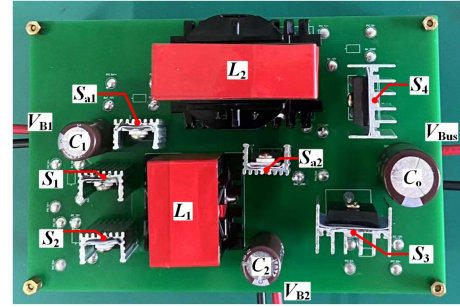


Fig. 20. Experimental prototype.

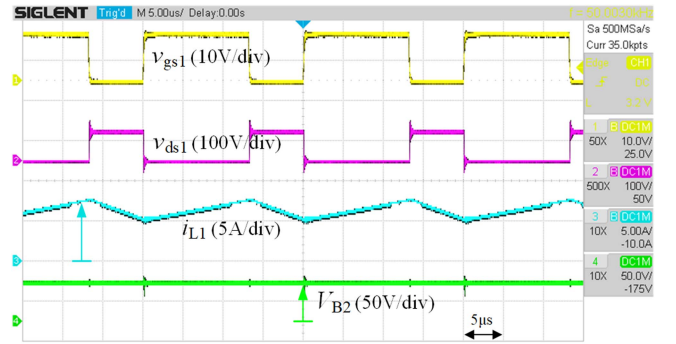


Fig. 21. Measured waveforms v_{gs1} , v_{ds1} , i_{L1} , and V_{B2} in Stage I under $P_{B2} = 300$ W from V_{B1} to V_{B2} .

IV. EXPERIMENT RESULTS

In a particular battery system with three ports, the battery banks have two port voltages of 72 V (port 1) and 48 V (port 2), and port 3 is a 200 V dc bus. Any two of the three ports can transfer energy to each other, and considering the voltage magnitude, any two ports are bidirectional buck/boost converters. Based on the above theoretical analysis, Fig. 15 is chosen as the topology and the laboratory prototype is built. The system specifications and key parameters are given in Table I. By setting the boundary conditions under $I_{B1,BCM} = 0.83$ A and $I_{Bus,BCM} = 0.3$ A, L_1 and L_2 are designed as 130 and 555 μ H from (8) and (9), respectively. The experimental prototype is shown in Fig. 20.

In stage I under full load conditions, Figs. 21 and 22 show the measured waveforms of v_{gs1} , v_{ds1} , i_{L1} , and V_{B2} when V_{B1} provides energy to V_{B2} , and v_{gs2} , v_{ds2} , i_{L1} , and V_{B1} when V_{B2} provides energy to V_{B1} , respectively. In stage II under full load

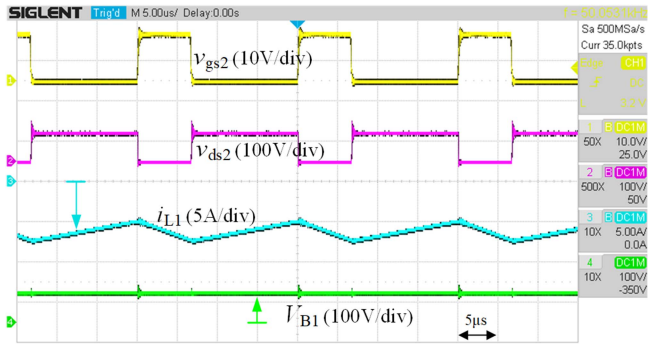


Fig. 22. Measured waveforms v_{gs2} , v_{ds2} , i_{L1} , and V_{B1} in Stage I under $P_{B1} = 300$ W from V_{B2} to V_{B1} .

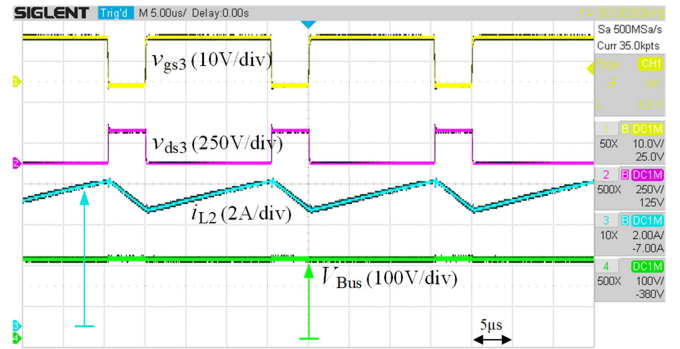


Fig. 25. Measured waveforms v_{gs3} , v_{ds3} , i_{L2} , and V_{Bus} in Stage III under $P_{Bus} = 300$ W from V_{B2} to V_{Bus} .

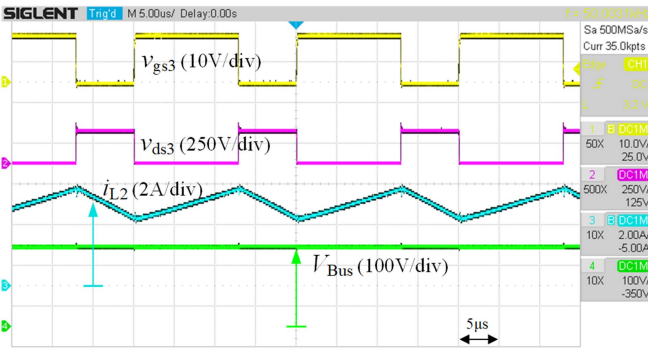


Fig. 23. Measured waveforms v_{gs3} , v_{ds3} , i_{L2} , and V_{Bus} in Stage II under $P_{Bus} = 300$ W from V_{B1} to V_{Bus} .

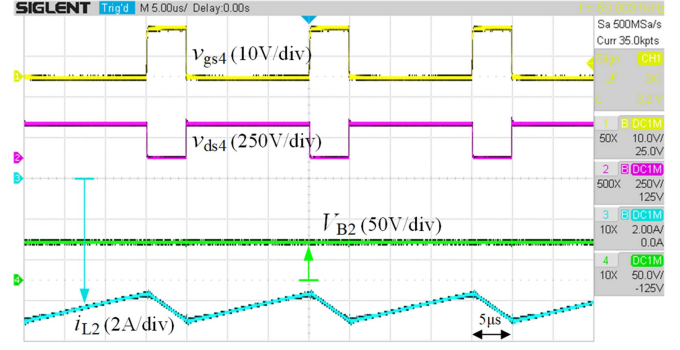


Fig. 26. Measured waveforms v_{gs4} , v_{ds4} , i_{L2} , and V_{B2} in Stage III under $P_{B2} = 300$ W from V_{Bus} to V_{B2} .

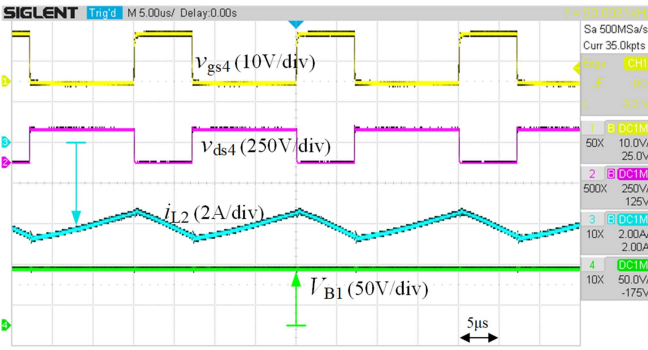
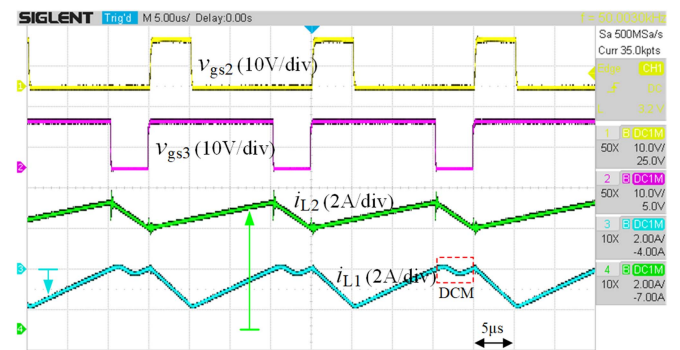
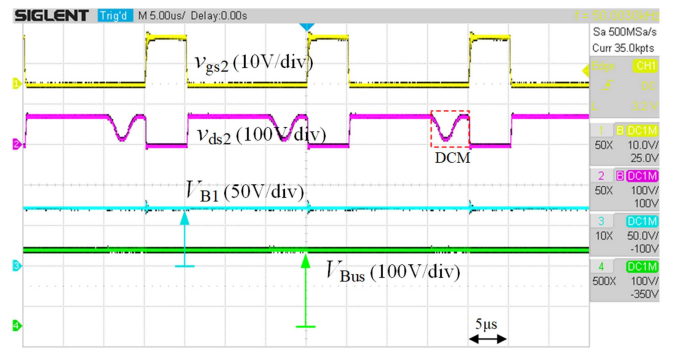


Fig. 24. Measured waveforms v_{gs4} , v_{ds4} , i_{L2} , and V_{B1} in Stage II under $P_{B1} = 300$ W from V_{Bus} to V_{B1} .



(a)



(b)

Fig. 27. Measured waveforms with (a) v_{gs2} , v_{gs3} , i_{L1} , and i_{L2} and (b) v_{gs2} , v_{ds2} , V_{B1} , and V_{Bus} in stage IV under $P_{B1} = 30$ W and $P_{Bus} = 270$ W from V_{B2} to V_{B1} and V_{Bus} .

conditions, Figs. 23 and 24 show measured waveforms of v_{gs3} , v_{ds3} , i_{L2} , and V_{Bus} when V_{B1} provides energy to V_{Bus} , and v_{gs4} , v_{ds4} , i_{L2} , and V_{B1} when V_{Bus} provides energy to V_{B1} . In stage III under full load conditions, Figs. 25 and 26 show measured waveforms of v_{gs3} , v_{ds3} , i_{L2} , and V_{Bus} when V_{B2} provides energy to V_{Bus} , and v_{gs4} , v_{ds4} , i_{L2} , and V_{B2} when V_{Bus} provides energy to V_{B2} . These experimental waveforms indicate that the proposed converter can achieve bidirectional energy transfer between any two ports. In stage IV, when V_{B2} provides energy to V_{B1} and V_{Bus} , Figs. 27 and 28 show the measured waveforms of v_{gs2} , v_{gs3} , i_{L1} , i_{L2} , v_{ds2} , V_{B1} , and V_{Bus} under $P_{B1} = 30$ W and $P_{Bus} = 270$ W, and $P_{B1} = 270$ W and $P_{Bus} = 30$ W, respectively. In Fig. 27, from V_{B2} to V_{Bus} ,

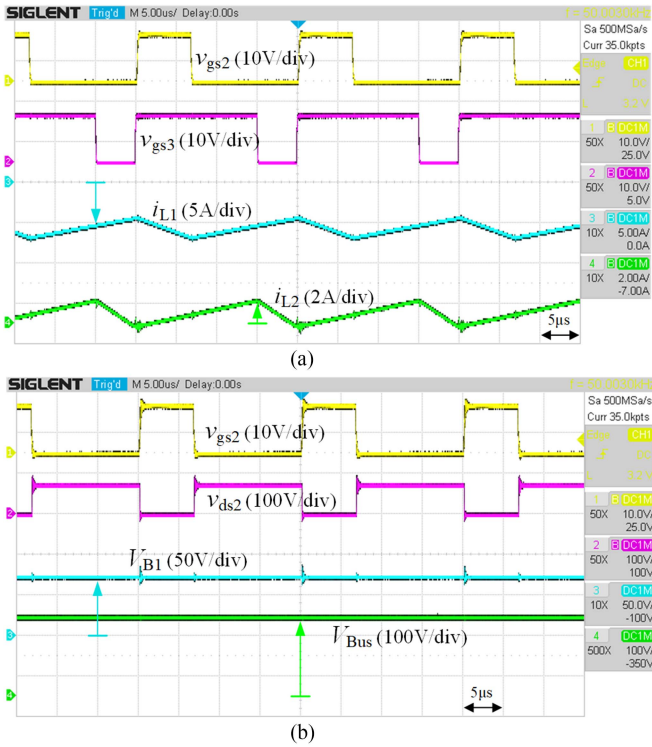


Fig. 28. Measured waveforms with (a) v_{gs2} , v_{gs3} , i_{L1} , and i_{L2} and (b) v_{gs2} , v_{ds2} , V_{B1} , and V_{Bus} in stage IV under $P_{B1} = 270$ W and $P_{Bus} = 30$ W from V_{B2} to V_{B1} and V_{Bus} .

after i_{L1} changes from a negative maximum value to zero, inductor L_1 resonates with the output capacitors of S_1 and S_2 due to operation in discontinuous conduction mode (DCM). The independent power flow controls of V_{B2} to V_{B1} and V_{B2} to V_{Bus} are achieved. Moreover, in Fig. 27, i_{L1} is operated in DCM); therefore, L_1 resonates with the output capacitor of S_2 . Fig. 29(a) and (b) shows the measured waveforms v_{gsa1} , v_{gs3} , i_{L2} , and V_{Bus} in stage V from V_{B1} and V_{B2} to V_{Bus} under $P_{B1} = 270$ W and $P_{B2} = 30$ W, and $P_{B1} = 30$ W and $P_{B2} = 270$ W, respectively. When S_{a1} is turned ON and OFF, V_{B1} and V_{B2} transfer energy to V_{Bus} independently. By building the simulation model in MATLAB/Simulink, the mode transitions waveform is shown in Fig. 30. In SIDO mode, V_{B1} provides total power of 300 W to V_{B2} and V_{Bus} ; the charging power to V_{B2} is 150 W ($i_{B2} = 3.125$ A) and the load power to V_{Bus} is also 150 W ($i_{Bus} = 0.75$ A). When load power increases to 300 W ($i_{Bus} = 1.5$ A), S_1 is turned OFF, and both V_{B1} and V_{B2} provide 150 W ($i_{B1} = 2.08$ A and $i_{B2} = 3.125$ A); then the converter changes to DISO mode.

Fig. 31 shows the measured efficiency curves of stages I–III. The power flows between V_{B1} and V_{B2} have higher efficiency, and the peak efficiency is 98.4% from V_{B1} to V_{B2} . Moreover, compared with stage II, the the increased duty cycle in stage III causes more conduction losses, decreasing the efficiency. The efficiency in DISO and SIDO modes is obtained by combining the SISO modes. For example, in SIDO mode, V_{B1} provides 30 and 270 W of energy to V_{B2} and V_{Bus} , respectively, and the efficiency 97.8% of stage I at 30 W and the efficiency 98.1% of

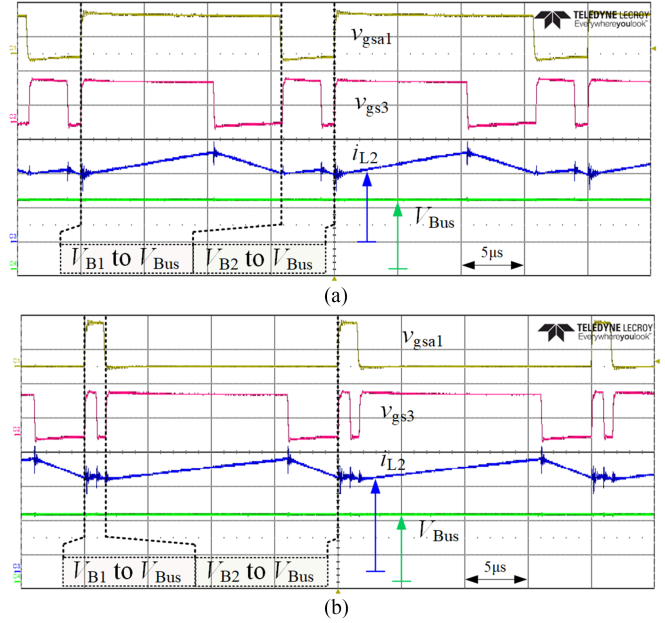


Fig. 29. Measured waveforms v_{gsa1} , v_{gs3} , i_{L2} , and V_{Bus} in stage V from V_{B1} and V_{B2} to V_{Bus} under (a) $P_{B1} = 270$ W and $P_{B2} = 30$ W and (b) $P_{B1} = 30$ W and $P_{B2} = 270$ W.

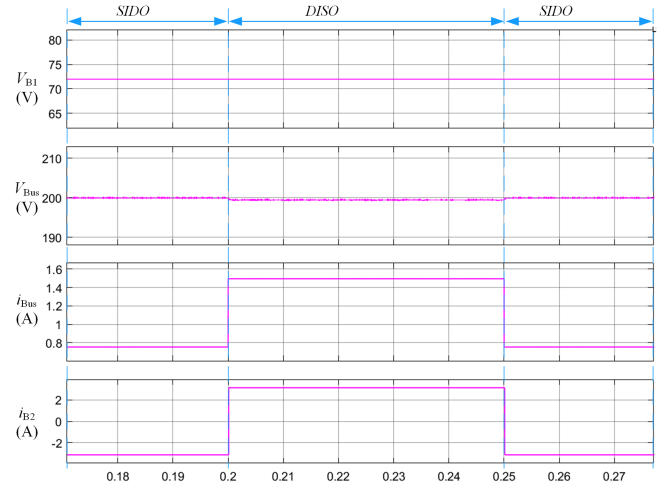


Fig. 30. Mode transitions between SIDO and DISO modes.

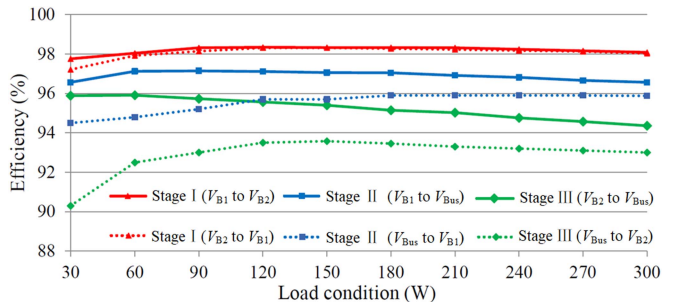


Fig. 31. Efficiency curves.

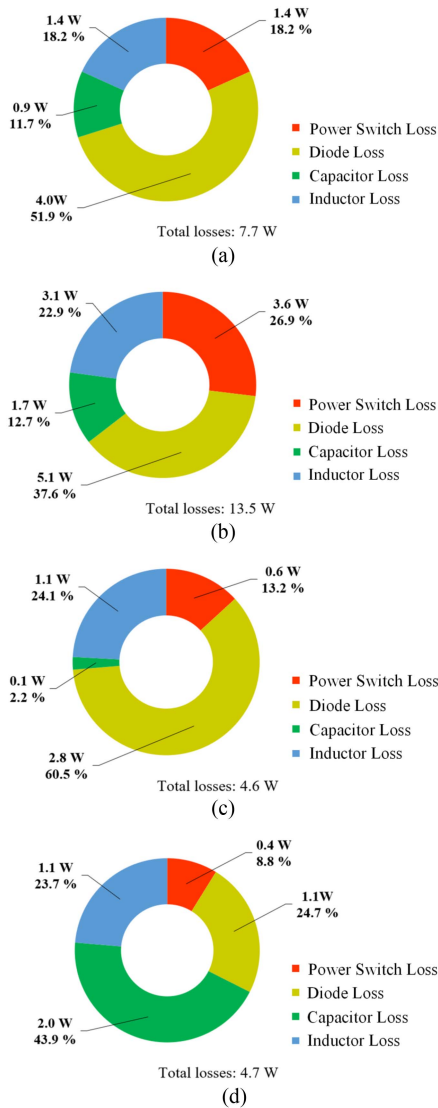


Fig. 32. Loss breakdown analyses under full load of (a) V_{B1} to V_{BUS} , (b) V_{B2} to V_{BUS} , (c) V_{B1} to V_{B2} , and (d) V_{B2} to V_{B1} .

stage II at 270 W are weighted to obtain the efficiency 98.07%; in DISO mode, when V_{B1} and V_{B2} provide 270 and 30 W of energy to V_{BUS} , respectively, the efficiency 98.1% of stage II at 270 W and the efficiency 90.4% of stage III at 30 W are weighted to obtain the efficiency 97.3%. The efficiency curves in Fig. 31 are highly affected by the boundary conditions of L_1 and L_2 . Since the efficiency under step-down operation of the built BTPC is low, the boundary conditions of L_1 and L_2 are designed to obtain the highest efficiency near 50% from V_{BUS} to V_{B1} and V_{BUS} to V_{B2} load conditions. Under V_{B1} to V_{BUS} , V_{B2} to V_{BUS} , V_{B1} to V_{B2} , and V_{B2} to V_{B1} , the loss breakdown analyses of the experiments result under full load condition are shown in Fig. 32(a)–(d), respectively. Diode loss represents the antiparallel diode with current flowing through the power switch turned OFF.

V. CONCLUSION

To achieve systematic topology derivation for TPCs and BTPCs with independent power transferring, two systematic

converter synthesis methods are proposed by adding one power switch and one diode, and two power switches, respectively. Thus, by combining the basic converters via proposed methods, a series of TPCs and BTPCs including nonisolated and isolated converters are derived. The derived converters offer benefits in terms of their simpler structures and independent power flow control. In addition, these converters can be applied in power supply systems with multiple sources or battery energy storage, such as distributed generation, hybrid electric, and fuel cell vehicles, among others—where engineers can easily obtain an appropriate architecture for specific applications. Finally, one of the nonisolated BTPCs with a common ground was analyzed and built to verify the feasibility of the proposed converter.

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