

# Letters

## Analytically Assessing the Effect of Strength on Temporary Overvoltage in Hybrid Multi-Infeed HVdc Systems

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**Abstract**—In hybrid multi-infeed HVdc (HMIDC) systems comprising both voltage-source and line-commutated converters' inverters, the strength has a significant effect on the temporary overvoltage (TOV). However, this effect has always been assessed by the simulated approach in earlier works. It is unable to provide the sufficiently theoretical perspectives and also time-consuming as onerous electromagnetic transient simulations are required. Therefore, in this letter, the mathematical expression of the TOV is first derived as the analytical function of the hybrid multi-infeed interactive effective short-circuit ratio (HMIESCR) strength index. This derivation is achieved by using the quasi-steady-state analytical model of HMIDC systems with the interinverter interactions considered. Then, the derived expression is utilized for analytically assessing the effect of the HMIESCR on the TOV versus various system parameters and operation variables. Compared to the simulated approach, the proposed analytical approach here can offer more sufficiently theoretical perspectives and is also more efficient as simulations are no more required. Finally, the experimental results of a hybrid tri-infeed HVdc test system based on the hardware-in-the-loop platform validate the analytical approach.

**Index Terms**—Hybrid multi-infeed HVdc (HMIDC) systems, hybrid multi-infeed interactive effective short-circuit ratio (HMIESCR), interinverter interactions, strength, temporary overvoltage (TOV).

### I. INTRODUCTION

RECENTLY, hybrid multi-infeed HVdc (HMIDC) systems have been increasingly arising where both voltage-source and line-commutated converters (VSC and LCC) are located at various inverter ac buses in the common receiving end ac

network [1]–[3]. One typical example of such systems is China Guangdong Power Grid in 2021 including one newly commissioned VSC and nine LCC inverters [4], [5]. In HMIDC systems, the blocking of the LCC inverter due to disturbances such as ac and dc faults may cause the temporary overvoltage (TOV) at the concerned inverter ac bus. The higher TOV will impose a great threat to the electrical equipment security in the LCC inverter such as thyristor valves, converter transformers, and reactive power compensators [6], [7]. Besides, the TOV is expected to be significantly affected by the strength since the latter essentially quantifies the voltage support capability of the receiving end ac network to the normal operation of the concerned LCC inverter [6]. Thereby, it is very helpful to assess the effect of the strength on the TOV in HMIDC systems.

The initial research on the effect of the strength on the TOV has been mainly conducted in single-infeed LCC-HVdc systems including only single inverter. Therein, the classical effective short-circuit ratio (ESCR) strength index is identified to affect the TOV inversely in the IEEE Standard 1204-1997 through the parametric analysis [7]. Buoyed by the extensive application of the ESCR in single-infeed LCC-HVdc systems, its further usage for the TOV study in multi-infeed LCC-HVdc systems has been subsequently explored [8]. However, this exploration indicates that the ESCR cannot be effectively utilized for the accurate prediction of the TOV. This is because the interinverter interactions existing among multiple LCC inverters within the common receiving end ac network are not considered in the definition of the ESCR concept. To address such issue, the multi-infeed interaction factor (MIIF) index is therefore developed to quantify the interinverter interactions in multi-infeed LCC-HVdc systems by the CIGRE Working Group B4.41 [6]. The use of the MIIF then enables the multi-infeed interactive ESCR (MIIESCR) strength index to be further proposed [6]. Thereafter, the MIIESCR is also reported to affect the TOV with an inverse relationship by the simulated analysis [6], [9]. Nevertheless, the above conclusions as to the impact of the strength on the TOV in multi-infeed LCC-HVdc systems cannot be directly extended into the concerned HMIDC systems in this letter. This is caused by the fact that there are more complex interinverter interactions in HMIDC systems since VSC and LCC inverters have obviously different operation principles and consequently various electrical characteristics [5].

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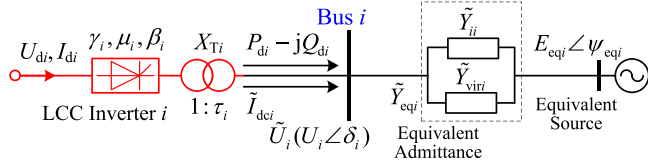
$$\begin{aligned}
\text{TOV}_i &= \sqrt{U_i^2 + \frac{P_{di}^2 + Q_{di}^2}{U_i^2 Y_{eqi}^2} + \frac{2Q_{di}}{Y_{eqi}}} \\
&= \sqrt{U_i^2 + \frac{P_{di}^2 + Q_{di}^2}{U_i^2 P_{di}^2 \cdot \text{HMIESCR}_i^2 / U_i^4} + \frac{2Q_{di}}{P_{di} \cdot \text{HMIESCR}_i / U_i^2}} \\
&= U_i \sqrt{1 + \frac{2Q_{di}}{P_{di}} \cdot \frac{1}{\text{HMIESCR}_i} + \frac{P_{di}^2 + Q_{di}^2}{P_{di}^2} \cdot \frac{1}{\text{HMIESCR}_i^2}}.
\end{aligned}$$


Fig. 2. Equivalent single-infeed LCC-HVdc model of HMIDC systems referred at LCC inverter ac bus  $i$ .

where  $\tilde{Y}_{ij}$  represents the nodal mutual-admittance matrix element between inverter ac buses  $j$  ( $j \in \{1, 2, \dots, n-1, n\}$ ,  $j \neq i$ ) and  $i$ . Meanwhile,  $\text{MVIF}_{ji}$  is defined as the ratio of the magnitudes of the voltage vector changes at inverter ac buses  $j$  and  $i$  in Fig. 1 (i.e.,  $|\Delta \tilde{U}_j|/|\Delta \tilde{U}_i|$ ) and utilized for quantifying the interactions between inverters  $j$  and  $i$  in HMIDC systems [12]. Note also that  $E_{eqi} \angle \psi_{eqi}$  in Fig. 2 is the equivalent source of HMIDC systems referred at LCC inverter ac bus  $i$ . When  $\tilde{U}_i$  is taken as the reference vector and considering that  $\tilde{Y}_{eqi}$  is almost inductive in the high voltage ac network,  $E_{eqi} \angle \psi_{eqi}$  is then calculated as [13]

$$\begin{aligned}
E_{eqi} \angle \psi_{eqi} &= \tilde{U}_i - \frac{\tilde{I}_{dci}}{\tilde{Y}_{eqi}} \approx U_i - \frac{(P_{di} - jQ_{di})^* / U_i}{-jY_{eqi}} \\
&= U_i - \frac{j(P_{di} + jQ_{di}) / U_i}{Y_{eqi}} = U_i + \frac{Q_{di}}{U_i Y_{eqi}} - j \frac{P_{di}}{U_i Y_{eqi}}. \quad (2)
\end{aligned}$$

In (2), the asterisk denotes the conjugate electrical quantity.

With the development of (2), it is known that  $\text{TOV}_i$  is actually equal to  $E_{eqi}$  when considering the system quasi-steady-state analytical model and thus can be calculated as

$$\begin{aligned}
\text{TOV}_i = E_{eqi} &= \sqrt{\left(U_i + \frac{Q_{di}}{U_i Y_{eqi}}\right)^2 + \left(\frac{P_{di}}{U_i Y_{eqi}}\right)^2} \\
&= \sqrt{U_i^2 + \left(\frac{Q_{di}}{U_i Y_{eqi}}\right)^2 + \frac{2Q_{di}}{Y_{eqi}} + \left(\frac{P_{di}}{U_i Y_{eqi}}\right)^2} \\
&= \sqrt{U_i^2 + \frac{P_{di}^2 + Q_{di}^2}{U_i^2 Y_{eqi}^2} + \frac{2Q_{di}}{Y_{eqi}}}. \quad (3)
\end{aligned}$$

It is worth mentioning that  $\text{HMIESCR}_i$  has been proposed to accurately depict the strength of HMIDC systems referred at LCC inverter ac bus  $i$  [13]. The mathematical expression of  $\text{HMIESCR}_i$  referring to Fig. 2 is given as

$$\text{HMIESCR}_i = \frac{U_i^2 Y_{eqi}}{P_{di}}. \quad (4)$$

From which it is derived that

$$Y_{eqi} = \frac{\text{HMIESCR}_i \cdot P_{di}}{U_i^2}. \quad (5)$$

Substituting (5) into (3) finally gives the mathematical expression of  $\text{TOV}_i$  as the analytical function of  $\text{HMIESCR}_i$  as

$$\begin{aligned}
\text{TOV}_i &= \sqrt{U_i^2 + \frac{P_{di}^2 + Q_{di}^2}{U_i^2 Y_{eqi}^2} + \frac{2Q_{di}}{Y_{eqi}}} \\
&= \sqrt{U_i^2 + \frac{P_{di}^2 + Q_{di}^2}{U_i^2 P_{di}^2 \cdot \text{HMIESCR}_i^2 / U_i^4} + \frac{2Q_{di}}{P_{di} \cdot \text{HMIESCR}_i / U_i^2}} \\
&= U_i \sqrt{1 + \frac{2Q_{di}}{P_{di}} \cdot \frac{1}{\text{HMIESCR}_i} + \frac{P_{di}^2 + Q_{di}^2}{P_{di}^2} \cdot \frac{1}{\text{HMIESCR}_i^2}}. \quad (6)
\end{aligned}$$

### C. On the Generalization

Since the TOV issue at LCC inverter ac buses due to the blocking of the LCC inverters is generally more serious than at VSC buses when VSC inverters are blocked, the primary focus in this letter has been put on LCC inverters in HMIDC systems. However, the theoretical analysis and derived equations in this section are still suitable for the TOV assessment at VSC buses if the blocking of the VSC inverters is further considered. This assertion can also be inferred from the related theoretical developments in the previous discussions, since there is no change on the final TOV mathematical expression in (6) even when the concerned LCC inverter is replaced by VSC. In other words, the derived (6) is actually generalized for the arbitrary case no matter when VSC or LCC inverters are concerned in the TOV analysis. Note also that in the analytical assessment of the TOV, the electrical quantities of  $P_d$ ,  $Q_d$ , and  $\text{HMIESCR}$  should be provided for VSC or LCC inverters as can be clearly seen in the generalized (6).

## III. ANALYTICALLY ASSESSING THE EFFECT OF THE HMIESCR ON THE TOV

### A. Introduction of the Hybrid Tri-Infeed HVdc Test System

The hybrid tri-infeed HVdc test system (i.e.,  $n = 3$  in Fig. 1) is used for the analytical assessment here. In the test system, LCC inverters 1 and 2 feed power to ac buses 1 and 2, respectively, with the combination of the constant dc current and extinction angle control modes adopted. Also, VSC inverter 3 terminates at ac bus 3 with the combination of the constant active power and ac voltage control modes utilized. Moreover, the system parameters and operation variables for both LCC inverters are selected to be the same as in the CIGRE HVdc Benchmark Model [14], [15]. Meanwhile,  $z_3 \angle \theta_3 = 0.5 \angle 74.96^\circ \text{p.u.}$ ,  $z_{12} \angle \theta_{12} = z_{13} \angle \theta_{13} = z_{23} \angle \theta_{23} = 1.5 \angle 80.54^\circ \text{p.u.}$ ,  $X_{T3} = 0.15 \text{ p.u.}$ ,  $\tau_3 = 1.0 \text{ p.u.}$ ,  $P_{d3} = 0.6 \text{ p.u.}$ ,  $Q_{d3} = -0.2 \text{ p.u.}$  Note that when these values are changed subsequently, they are illustrated in the related explanations.

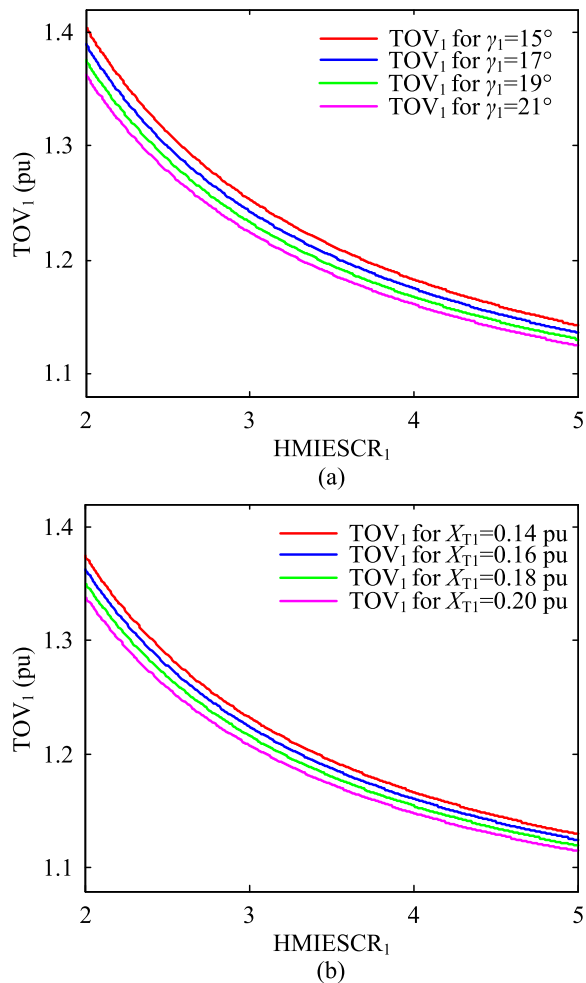


Fig. 3. Variation characteristics of TOV<sub>1</sub> versus HMIESCR<sub>1</sub> in the test system. (a) For each selected  $\gamma_1$ . (b) For each selected  $X_{T1}$ .

### B. Analytically Assessing the Effect

The derived expression (6) is further used for analytically assessing the effect of the HMIESCR on the TOV versus various system parameters and operation variables in the test system based on the MATLAB program. For such purpose, consider TOV<sub>1</sub> at LCC inverter ac bus 1 for the blocking of LCC inverter 1. When the extinction angle of LCC inverter 1 ( $\gamma_1$ ) is varied in the typical range from 15° to 21°, the variation characteristics of TOV<sub>1</sub> versus HMIESCR<sub>1</sub> are calculated using (6) and shown in Fig. 3(a). These characteristics are also given in Fig. 3(b) for the converter transformer leakage reactance ( $X_{T1}$ ) changing in the typical range from 0.14 to 0.20 p.u. As can be first seen in Fig. 3(a) and (b), TOV<sub>1</sub> monotonically decreases along with the increasing HMIESCR<sub>1</sub> for each selected  $\gamma_1$  or  $X_{T1}$ . This is understandable as a larger HMIESCR<sub>1</sub> means the stronger voltage support capability of the receiving end ac network to LCC inverter 1 at the concerned ac bus 1. Thus, a decreased TOV<sub>1</sub> is expected. Second, it is observed that the TOV<sub>1</sub>-HMIESCR<sub>1</sub> curve is higher for a larger  $\gamma_1$  or  $X_{T1}$ . This is because a larger  $\gamma_1$  or  $X_{T1}$  indicates a higher  $Q_{d1}$  and hence greater TOV<sub>1</sub> under the certain HMIESCR<sub>1</sub> as inferred in (6). From the above

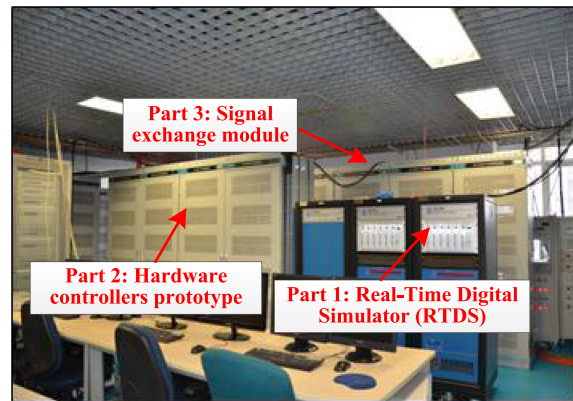


Fig. 4. Hardware-in-the-loop platform for the experimental results.

discussions, it is clearly concluded that the HMIESCR has an inverse effect on the TOV in the test system.

## IV. EXPERIMENTAL RESULTS

### A. Description of the Hardware-in-the-Loop Platform

The hardware-in-the-loop platform for the experimental results of the test system in Section III-A is presented in Fig. 4, which comprises three separate parts. Part 1 represents the extensively used real-time digital simulator (RTDS) where the ac/dc main circuits such as dc lines, converters, transformers, reactive power compensators, and ac network are modeled. Moreover, Part 2 is the hardware prototype of the dc controllers for the control mode combination described previously. Meanwhile, the signal exchange module between Parts 1 and 2 is realized in Part 3 by using the analog-in and analog-out cards. More precisely, these signals include the dc current, extinction angle of LCC inverters 1 and 2, active power and ac bus voltage of VSC inverter 3.

### B. Experimental Validation

Consider TOV<sub>1</sub> at LCC inverter ac bus 1 in the test system when LCC inverter 1 is blocked at  $t = 1.2$  s in the hardware-in-the-loop platform in Fig. 4. Then for the variation of HMIESCR<sub>1</sub> in the pre-set range of interest from 2 to 5 with the steps of 1, TOV<sub>1</sub> for each selected  $\gamma_1$  or  $X_{T1}$  is analytically calculated by (6) and shown in Tables I and II, respectively. In fact, these calculated values can also be obtained by referring to Fig. 3(a) and (b). For comparisons, the experimental TOV<sub>1</sub> is also observed accordingly for every HMIESCR<sub>1</sub>. It is clearly seen in Tables I and II that the maximum errors between the calculated and experimental TOV<sub>1</sub> are 5.4% and 5.5%, respectively (marked by the bold font). These errors are deemed to be small enough for guiding the planning and operation of the practical HMIDC systems. In other words, the derived (6) and also analytical approach in Sections II and III are effectively validated by the experimental results of the test system.

TABLE I  
EXPERIMENTAL RESULTS ON  $TOV_1$  VERSUS  $HMIESCR_1$  IN THE TEST SYSTEM  
FOR EACH SELECTED  $\gamma_1$

$HMIESCR_1$		2	3	4	5
$TOV_1$ for $\gamma_1=15^\circ$	Cal.	1.363	1.225	1.161	1.125
	Exp.	1.293	1.174	1.124	1.073
	Err.	5.4 %	4.3 %	3.3 %	4.8 %
$TOV_1$ for $\gamma_1=17^\circ$	Cal.	1.376	1.234	1.168	1.130
	Exp.	1.324	1.189	1.117	1.075
	Err.	3.9 %	3.8 %	4.6 %	5.1 %
$TOV_1$ for $\gamma_1=19^\circ$	Cal.	1.390	1.243	1.175	1.136
	Exp.	1.321	1.186	1.133	1.093
	Err.	5.2 %	4.8 %	3.7 %	3.9 %
$TOV_1$ for $\gamma_1=21^\circ$	Cal.	1.405	1.254	1.183	1.143
	Exp.	1.348	1.198	1.136	1.090
	Err.	4.2 %	4.7 %	4.1 %	4.9 %

Cal.: Calculated. Exp.: Experimental. Err.: Error. Err. = |Cal. - Exp.)/Exp.

TABLE II  
EXPERIMENTAL RESULTS ON  $TOV_1$  VERSUS  $HMIESCR_1$  IN THE TEST SYSTEM  
FOR EACH SELECTED  $X_{T1}$

$HMIESCR_1$		2	3	4	5
$TOV_1$ for $X_{T1}=0.14$ pu	Cal.	1.339	1.208	1.149	1.115
	Exp.	1.284	1.149	1.091	1.070
	Err.	4.3 %	5.1 %	5.3 %	4.2 %
$TOV_1$ for $X_{T1}=0.16$ pu	Cal.	1.351	1.217	1.155	1.120
	Exp.	1.309	1.162	1.095	1.068
	Err.	3.2 %	4.7 %	5.5 %	4.9 %
$TOV_1$ for $X_{T1}=0.18$ pu	Cal.	1.363	1.225	1.161	1.125
	Exp.	1.302	1.182	1.118	1.082
	Err.	4.7 %	3.6 %	3.8 %	4.0 %
$TOV_1$ for $X_{T1}=0.20$ pu	Cal.	1.374	1.233	1.167	1.130
	Exp.	1.314	1.182	1.109	1.079
	Err.	4.6 %	4.3 %	5.2 %	4.7 %

Cal.: Calculated. Exp.: Experimental. Err.: Error. Err. = |Cal. - Exp.)/Exp.

### C. Comparison With the Simulated Approach in Earlier Works

Although the research efforts have been made to evaluate the impact of the AISCR on the TOV in HMIDC systems [10], [11], this evaluation scheme is always achieved by the simulated approach. It is time-consuming because onerous electromagnetic transient simulations are required. For example, with simulations running on an Intel i7 processor, 1.80 GHz, 32.0 GB RAM personal laptop, it typically takes about 4 min to get the simulated  $TOV_1$  for each selected  $\gamma_1$  or  $X_{T1}$  under certain  $HMIESCR_1$  in Tables I and II for the test system. Therefore, 128 min (around 2 h) are totally required for the 32 cases under investigation in both tables by the simulated approach in earlier works [10], [11]. As a comparison, only 1.8 s are needed in total for all the analytical calculations in both tables using (6) by the proposed analytical approach in this letter. The above discussions hence illustrate that compared to the simulated approach, the analytical approach is more efficient as no time-consuming simulations are required at all. It is further worth mentioning that as the effect of  $HMIESCR_1$  on  $TOV_1$  in the test system is analytically assessed in a more direct manner using (6) rather than analyzed

by simulations, more sufficiently theoretical perspectives are able to be provided by the analytical approach.

## V. CONCLUSION

This letter first derived the mathematical expression of the TOV as the analytical function of the  $HMIESCR$  by using the quasi-steady-state model of HMIDC systems with the inter-inverter interactions quantified by the MVIF. Second, the derived expression was used for analytically assessing the effect of the  $HMIESCR$  on the TOV. Compared with the simulated approach in earlier works, the proposed analytical approach could offer more sufficiently theoretical perspectives and was also more efficient because no time-consuming simulations were required at all. Finally, the analytical approach was validated by the experimental results of a hybrid tri-infeed HVdc test system based on the hardware-in-the-loop platform.

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